

Course: Calculus (3)

Chapter: [12]

VECTOR-VALUED FUNCTIONS

Section: [12.1]

INTRODUCTION TO VECTOR-VALUED FUNCTIONS

## IN THIS CHAPTER

- ✓ We will consider *functions whose values are* **vectors**.

Functions that associate  
vectors with real numbers.

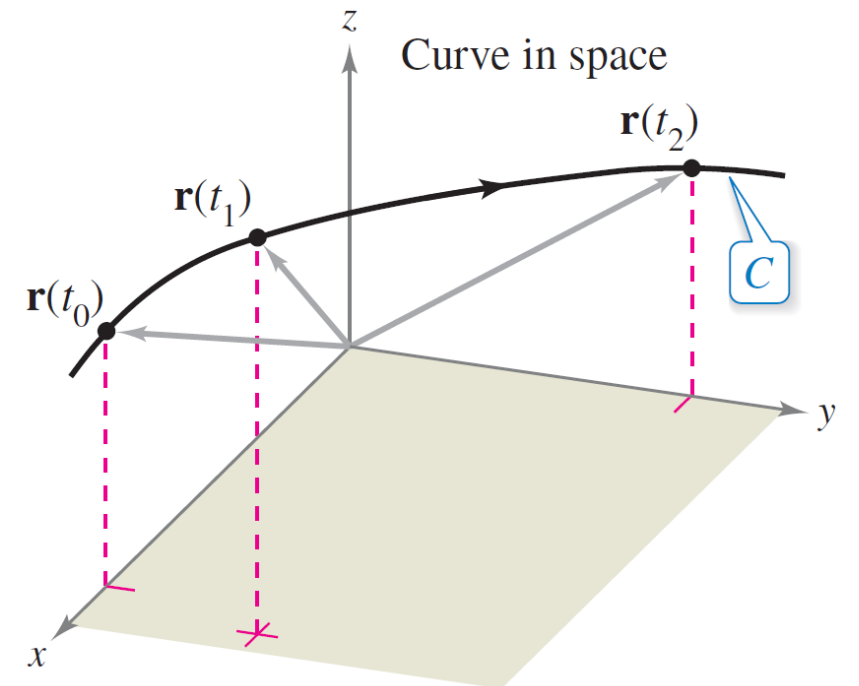
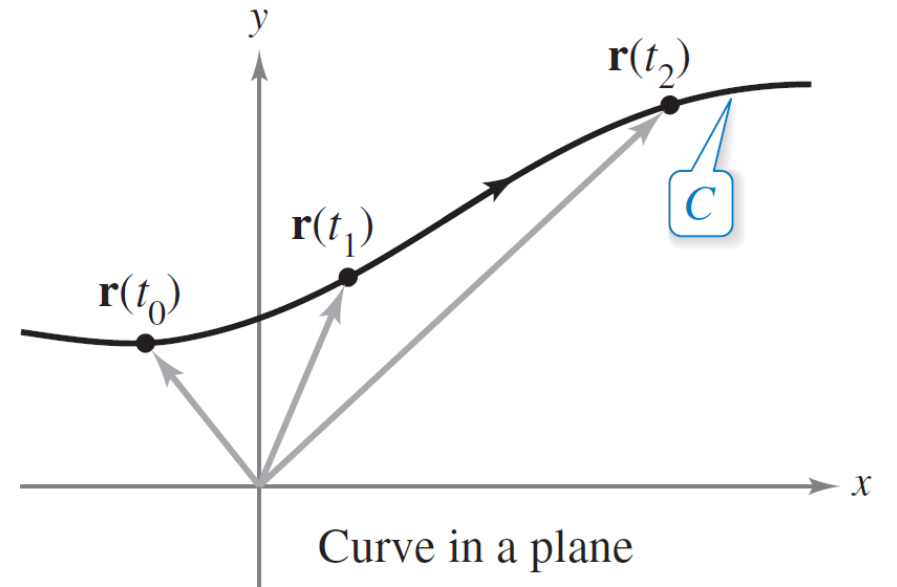
- ✓ In this section we will discuss more general parametric curves, and we will show how vector notation can be used to express parametric equations in a more compact form.

## VECTOR-VALUED FUNCTIONS

A function of the form

$$\begin{aligned}\mathbf{r}(t) &= f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k} \\ &= \langle f(t), g(t), h(t) \rangle\end{aligned}$$

is a **vector-valued function**, where the component functions  $f$ ,  $g$  and  $h$  are real-valued functions of the parameter  $t$ .



## PARAMETRIC CURVES IN 3 –SPACE

**Example** The parametric equations

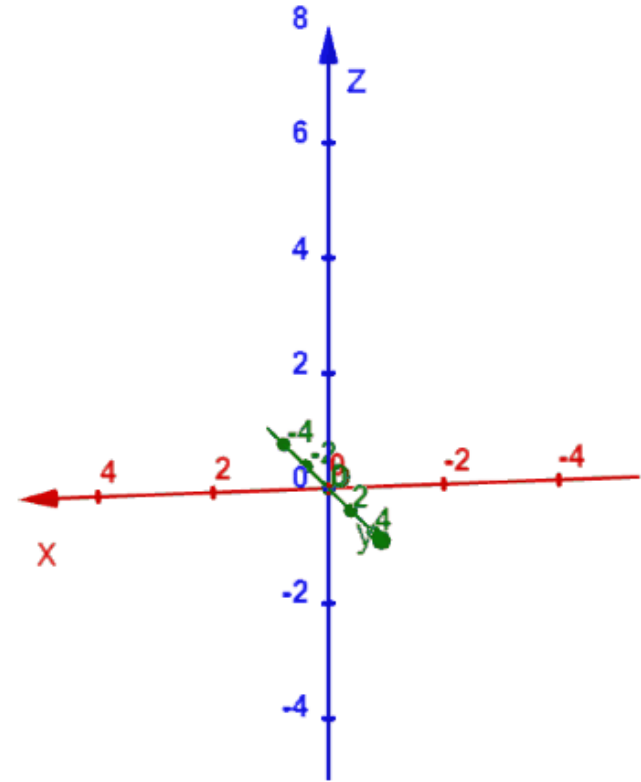
$$x = 1 - t$$

$$y = 3t$$

$$z = 2t$$

represent a line in 3 –space that passes through the point  $(1,0,0)$  and is parallel to the vector  $\langle -1, 3, 2 \rangle$ .

$$\begin{aligned} \mathbf{r}(t) &= (1 - t)\mathbf{i} + 3t\mathbf{j} + 2t\mathbf{k} \\ &= \langle 1 - t, 3t, 2t \rangle \end{aligned}$$



## PARAMETRIC CURVES IN 3 –SPACE

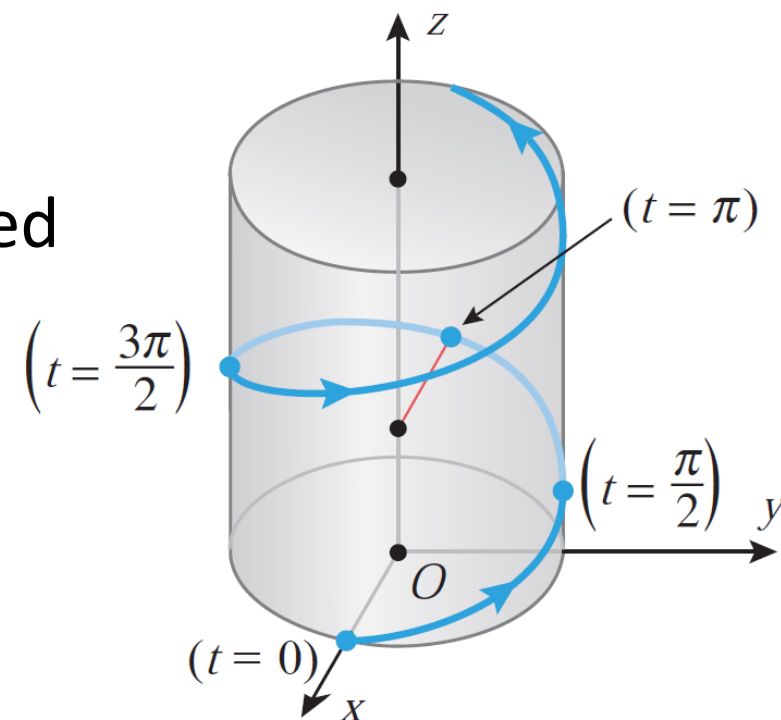
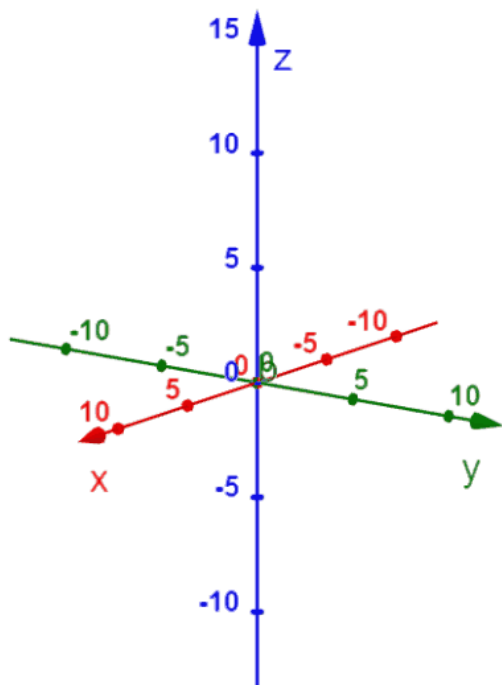
**Example** Describe the parametric curve represented by the equations

$$x = 10 \cos t$$

$$y = 10 \sin t$$

$$z = t$$

$$\mathbf{r}(t) = 10 \cos t \mathbf{i} + 10 \sin t \mathbf{j} + t \mathbf{k}$$
$$= \langle 10 \cos t, 10 \sin t, t \rangle$$



**Circular HELIX**

## VECTOR-VALUED FUNCTIONS

The **domain** of a vector-valued function  $\mathbf{r}(t)$  is the set of allowable values for  $t$ .

**NOTE** Usual reasons to restrict a domain:

1. Avoid division by 0.
2. Avoid even roots of negative numbers.
3. Avoid logarithms of negative numbers or 0.

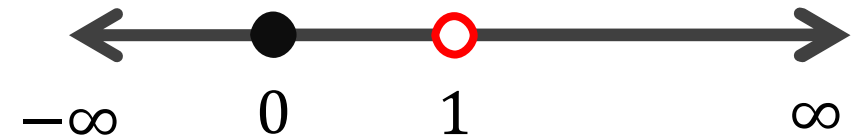
## VECTOR-VALUED FUNCTIONS

**Example** Find the natural domain of  $\mathbf{r}(t) = \ln|t - 1| \mathbf{i} + e^t \mathbf{j} + \sqrt{t} \mathbf{k}$

$x(t) = \ln|t - 1|$      Domain =  $\mathbb{R} - \{1\}$

$y(t) = e^t$      Domain =  $\mathbb{R}$

$z(t) = \sqrt{t}$      Domain =  $[0, \infty)$



$\therefore$  The domain of  $\mathbf{r}(t)$  is the *intersection of these sets*.

$[0, 1) \cup (1, \infty)$

Course: Calculus (3)

Chapter: [12]

VECTOR-VALUED FUNCTIONS

Section: [12.2]

CALCULUS OF VECTOR-VALUED FUNCTIONS



## LIMITS AND CONTINUITY

- Many techniques and definitions used in the calculus of real-valued functions can be applied to vector-valued functions.
- For instance, you can add and subtract vector-valued functions, multiply a vector-valued function by a scalar, take the limit of a vector-valued function, differentiate a vector-valued function, and so on.

## LIMITS AND CONTINUITY

$$\begin{aligned}\mathbf{r}_1(t) + \mathbf{r}_2(t) &= [f_1(t)\mathbf{i} + g_1(t)\mathbf{j}] + [f_2(t)\mathbf{i} + g_2(t)\mathbf{j}] \\ &= [f_1(t) + f_2(t)]\mathbf{i} + [g_1(t) + g_2(t)]\mathbf{j}.\end{aligned}$$

$$\begin{aligned}\mathbf{r}_1(t) - \mathbf{r}_2(t) &= [f_1(t)\mathbf{i} + g_1(t)\mathbf{j}] - [f_2(t)\mathbf{i} + g_2(t)\mathbf{j}] \\ &= [f_1(t) - f_2(t)]\mathbf{i} + [g_1(t) - g_2(t)]\mathbf{j}.\end{aligned}$$

$$\begin{aligned}c\mathbf{r}(t) &= c[f_1(t)\mathbf{i} + g_1(t)\mathbf{j}] \\ &= cf_1(t)\mathbf{i} + cg_1(t)\mathbf{j}.\end{aligned}$$

$$\begin{aligned}\frac{\mathbf{r}(t)}{c} &= \frac{[f_1(t)\mathbf{i} + g_1(t)\mathbf{j}]}{c}, \quad c \neq 0 \\ &= \frac{f_1(t)}{c}\mathbf{i} + \frac{g_1(t)}{c}\mathbf{j}.\end{aligned}$$

## LIMITS AND CONTINUITY

If  $\mathbf{r}$  is a vector-valued function such that  $\mathbf{r}(t) = f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$ , then

$$\lim_{t \rightarrow a} \mathbf{r}(t) = \left[ \lim_{t \rightarrow a} f(t) \right] \mathbf{i} + \left[ \lim_{t \rightarrow a} g(t) \right] \mathbf{j} + \left[ \lim_{t \rightarrow a} h(t) \right] \mathbf{k}$$

provided  $f$ ,  $g$ , and  $h$  have limits as  $t \rightarrow a$ .

**Example** If  $\mathbf{r}(t) = \frac{3}{t^2}\mathbf{i} + \frac{\ln t}{t^2 - 1}\mathbf{j} + \cos(\pi t)\mathbf{k}$ , find  $\lim_{t \rightarrow 1} \mathbf{r}(t)$ .

$$\begin{aligned} \lim_{t \rightarrow 1} \mathbf{r}(t) &= \left\langle 3, \frac{1}{2}, -1 \right\rangle \\ &= 3\mathbf{i} + \frac{1}{2}\mathbf{j} - \mathbf{k} \end{aligned}$$

$$\lim_{t \rightarrow 1} \frac{3}{t^2} = 3$$

$$\lim_{t \rightarrow 1} \frac{\ln t}{t^2 - 1} = \lim_{t \rightarrow 1} \frac{1/t}{2t} = \frac{1}{2}$$

$$\lim_{t \rightarrow 1} \cos(\pi t) = -1$$

## LIMITS AND CONTINUITY

**Example** If  $\mathbf{r}(t) = \frac{2t^2-1}{t^2+t} \mathbf{i} + \sin\left(\frac{1}{t}\right) \mathbf{j} + te^{-t} \mathbf{k}$ , find  $\lim_{t \rightarrow \infty} \mathbf{r}(t)$ .

$$\lim_{t \rightarrow \infty} \mathbf{r}(t) = \langle 2, 0, 0 \rangle = 2\mathbf{i}$$

$$\lim_{t \rightarrow \infty} \frac{2t^2 - 1}{t^2 + t} = 2$$

$$\lim_{t \rightarrow \infty} \sin\left(\frac{1}{t}\right) = 0$$

$$\lim_{t \rightarrow \infty} te^{-t} = 0 \cdot \infty$$

$$= \lim_{t \rightarrow \infty} \frac{t}{e^t} = \lim_{t \rightarrow \infty} \frac{1}{e^t} = 0$$

## LIMITS AND CONTINUITY

A vector-valued function  $\mathbf{r}$  is **continuous at the point** given by  $t = a$  when the limit of  $\mathbf{r}(t)$  exists as  $t \rightarrow a$  and

$$\lim_{t \rightarrow a} \mathbf{r}(t) = \mathbf{r}(a).$$

A vector-valued function  $\mathbf{r}$  is **continuous on an interval**  $I$  when it is continuous at every point in the interval.

**Example** The vector-valued function  $\mathbf{r}(t) = t^2\mathbf{i} + \frac{1}{t^2-1}\mathbf{j} + t\mathbf{k}$ , is discontinuous at  $t = \pm 1$ .

It is continuous for all  $t \in \mathbb{R} - \{-1, 1\}$

## DERIVATIVES

- The derivative of a vector-valued function is *defined by a limit* like that for the derivative of a real-valued function.

$$\mathbf{r}'(t) = \lim_{h \rightarrow 0} \frac{\mathbf{r}(t+h) - \mathbf{r}(t)}{h}$$

- The derivative of  $\mathbf{r}(t)$  can be *expressed as*

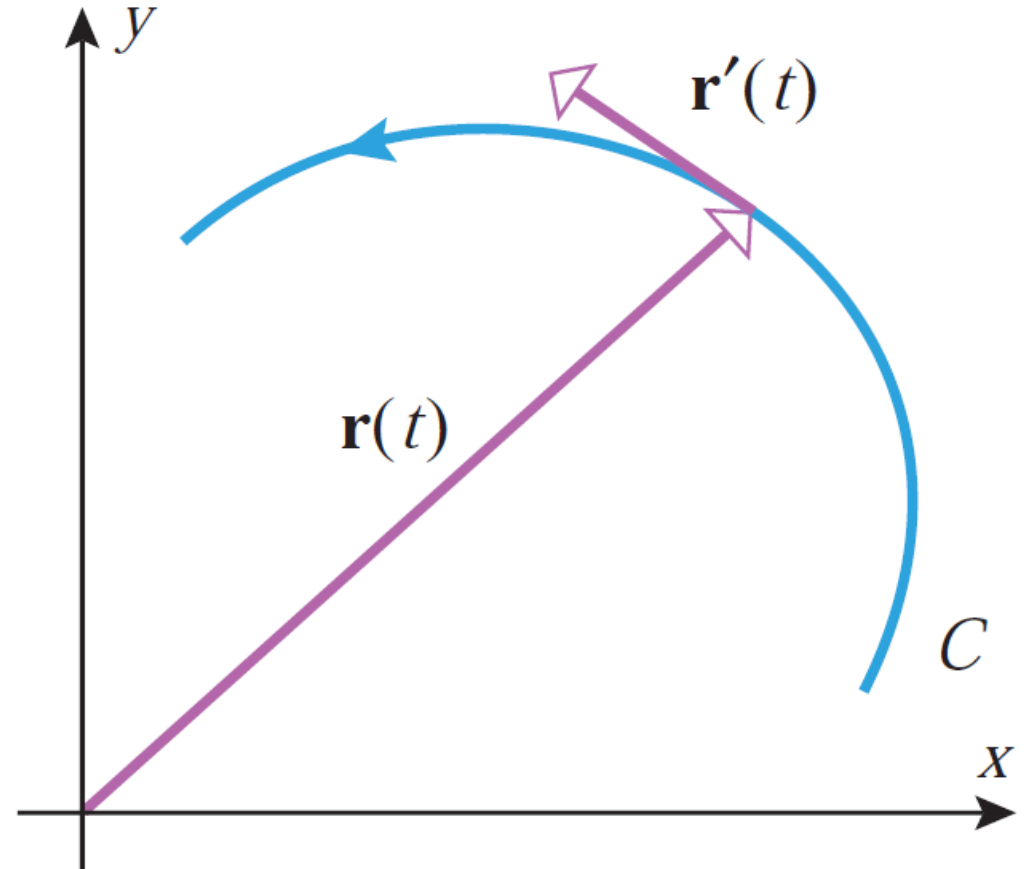
$$\frac{d}{dt} [\mathbf{r}(t)], \quad \frac{d\mathbf{r}}{dt}, \quad \mathbf{r}'(t), \quad \mathbf{r}'$$

- Keep in mind that  $\mathbf{r}(t)$  is a *vector*, not a number, and hence *has a magnitude and a direction* for each value of  $t$ , **except if**  $\mathbf{r}(t) = \mathbf{0}$ .

## DERIVATIVES

Suppose that  $C$  is the graph of a vector-valued function  $\mathbf{r}(t)$  and that  $\mathbf{r}'(t)$  exists and is nonzero for a given value of  $t$ .

If the vector  $\mathbf{r}'(t)$  is positioned with its initial point at the terminal point of the radius vector  $\mathbf{r}(t)$ , then  $\mathbf{r}'(t)$  is tangent to  $C$  and points in the direction of increasing parameter.



## DERIVATIVES

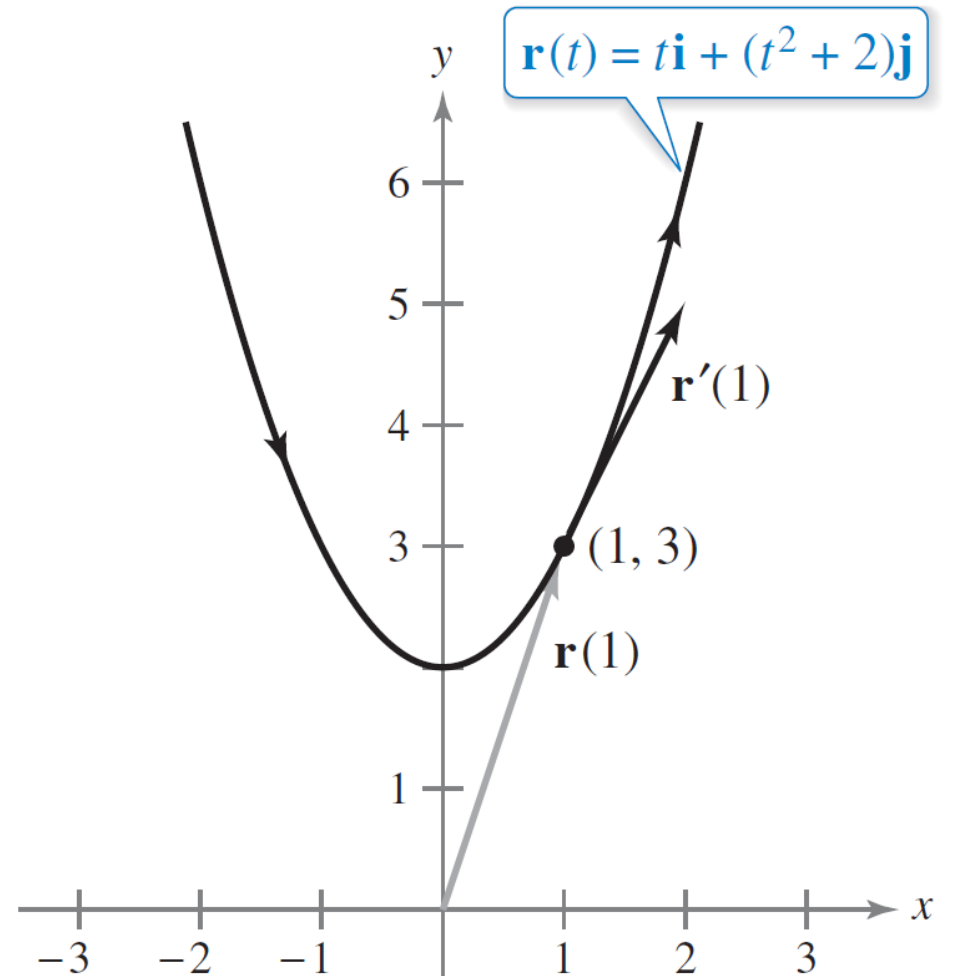
If  $\mathbf{r}(t) = f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$ , where  $f$ ,  $g$ , and  $h$  are differentiable functions of  $t$ , then

$$\mathbf{r}'(t) = f'(t)\mathbf{i} + g'(t)\mathbf{j} + h'(t)\mathbf{k}.$$

**Example** For the vector-valued function  $\mathbf{r}(t) = t\mathbf{i} + (t^2 + 2)\mathbf{j}$ , find  $\mathbf{r}'(1)$ .

$$\mathbf{r}'(t) = \mathbf{i} + 2t\mathbf{j}$$

$$\mathbf{r}'(1) = \mathbf{i} + 2\mathbf{j}$$





## DERIVATIVES

**Example** For the vector-valued function  $\mathbf{r}(t) = \cos t \mathbf{i} + \sin t \mathbf{j} + 2t\mathbf{k}$ , find:

1  $\mathbf{r}'(t)$   $\mathbf{r}'(t) = -\sin t \mathbf{i} + \cos t \mathbf{j} + 2\mathbf{k}$

2  $\mathbf{r}''(t)$   $\mathbf{r}''(t) = -\cos t \mathbf{i} - \sin t \mathbf{j}$

3  $\mathbf{r}'(t) \cdot \mathbf{r}''(t)$   $\mathbf{r}'(t) \cdot \mathbf{r}''(t) = \sin t \cos t - \cos t \sin t = 0$

4  $\mathbf{r}'(t) \times \mathbf{r}''(t)$

$$\mathbf{r}'(t) \times \mathbf{r}''(t) = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ -\sin t & \cos t & 2 \\ -\cos t & -\sin t & 0 \end{vmatrix} = 2 \sin t \mathbf{i} - 2 \cos t \mathbf{j} + \mathbf{k}$$

## DERIVATIVE RULES

1.  $\frac{d}{dt} [c\mathbf{r}(t)] = c\mathbf{r}'(t)$
2.  $\frac{d}{dt} [\mathbf{r}(t) \pm \mathbf{u}(t)] = \mathbf{r}'(t) \pm \mathbf{u}'(t)$
3.  $\frac{d}{dt} [w(t)\mathbf{r}(t)] = w(t)\mathbf{r}'(t) + w'(t)\mathbf{r}(t)$
4.  $\frac{d}{dt} [\mathbf{r}(t) \cdot \mathbf{u}(t)] = \mathbf{r}(t) \cdot \mathbf{u}'(t) + \mathbf{r}'(t) \cdot \mathbf{u}(t)$
5.  $\frac{d}{dt} [\mathbf{r}(t) \times \mathbf{u}(t)] = \mathbf{r}(t) \times \mathbf{u}'(t) + \mathbf{r}'(t) \times \mathbf{u}(t)$
6.  $\frac{d}{dt} [\mathbf{r}(w(t))] = \mathbf{r}'(w(t))w'(t)$
7. If  $\mathbf{r}(t) \cdot \mathbf{r}(t) = c$ , then  $\mathbf{r}(t) \cdot \mathbf{r}'(t) = 0$ .

## DERIVATIVE RULES

**Example** For  $\mathbf{u}(t) = \frac{1}{t}\mathbf{i} - \mathbf{j} + \ln t \mathbf{k}$  and  $\mathbf{v}(t) = t^2\mathbf{i} - 2t\mathbf{j} + \mathbf{k}$  then:

$$\begin{aligned} \textcircled{1} \quad \frac{d}{dt} [\mathbf{u}(t) \cdot \mathbf{v}(t)] &= \mathbf{u}(t) \cdot \mathbf{v}'(t) + \mathbf{u}'(t) \cdot \mathbf{v}(t) \\ &= \left\langle \frac{1}{t}, -1, \ln t \right\rangle \cdot \langle 2t, -2, 0 \rangle + \left\langle \frac{-1}{t^2}, 0, \frac{1}{t} \right\rangle \cdot \langle t^2, -2t, 1 \rangle \\ &= (2 + 2 + 0) + \left( -1 + 0 + \frac{1}{t} \right) \\ &= 3 + \frac{1}{t} \end{aligned}$$

## DERIVATIVE RULES

**Example** For  $\mathbf{u}(t) = \frac{1}{t}\mathbf{i} - \mathbf{j} + \ln t \mathbf{k}$  and  $\mathbf{v}(t) = t^2\mathbf{i} - 2t\mathbf{j} + \mathbf{k}$  then:

$$\begin{aligned} 2 \quad \frac{d}{dt} [\mathbf{v}(t) \times \mathbf{v}'(t)] &= \mathbf{v}(t) \times \mathbf{v}''(t) + \mathbf{v}'(t) \times \mathbf{v}'(t) \\ &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ t^2 & -2t & 1 \\ 2 & 0 & 0 \end{vmatrix} + \mathbf{0} \\ &= 2\mathbf{j} + 4t\mathbf{k} \end{aligned}$$

## TANGENT LINES TO GRAPHS OF VECTOR-VALUED FUNCTIONS

**Example** Find parametric equations of the tangent line to the circular helix  $\mathbf{r}(t) = \cos t \mathbf{i} + \sin t \mathbf{j} + t\mathbf{k}$  at the point where  $t = \pi$ .

$$t = \pi$$

**POINT**

$$(\cos \pi, \sin \pi, \pi) = (-1, 0, \pi)$$

**TANGENT VECTOR**

$$\mathbf{r}'(t) = -\sin t \mathbf{i} + \cos t \mathbf{j} + \mathbf{k}$$

$$\mathbf{r}'(\pi) = -\mathbf{j} + \mathbf{k}$$

$\therefore$  The parametric equations of the tangent line are

$$x = -1$$

$$y = -t$$

$$z = \pi + t$$

## DEFINITE AND INDEFINITE INTEGRALS OF VECTOR-VALUED FUNCTIONS

In general, we have

$$\int_a^b \mathbf{r}(t) dt = \left( \int_a^b x(t) dt \right) \mathbf{i} + \left( \int_a^b y(t) dt \right) \mathbf{j} + \left( \int_a^b z(t) dt \right) \mathbf{k}$$

**Example** Let  $\mathbf{r}(t) = t^2\mathbf{i} + e^t\mathbf{j} - 2 \cos(\pi t) \mathbf{k}$ . Then

$$\begin{aligned} \int_0^1 \mathbf{r}(t) dt &= \left( \int_0^1 t^2 dt \right) \mathbf{i} + \left( \int_0^1 e^t dt \right) \mathbf{j} - \left( \int_0^1 2 \cos \pi t dt \right) \mathbf{k} \\ &= \frac{t^3}{3} \Big|_0^1 \mathbf{i} + e^t \Big|_0^1 \mathbf{j} - \frac{2}{\pi} \sin \pi t \Big|_0^1 \mathbf{k} = \frac{1}{3} \mathbf{i} + (e - 1) \mathbf{j} \end{aligned}$$

## DEFINITE AND INDEFINITE INTEGRALS OF VECTOR-VALUED FUNCTIONS

**Example** 
$$\int (2t\mathbf{i} + 3t^2\mathbf{j}) dt = \left( \int 2t dt \right) \mathbf{i} + \left( \int 3t^2 dt \right) \mathbf{j}$$
$$= (t^2 + C_1)\mathbf{i} + (t^3 + C_2)\mathbf{j}$$
$$= (t^2\mathbf{i} + t^3\mathbf{j}) + (C_1\mathbf{i} + C_2\mathbf{j}) = (t^2\mathbf{i} + t^3\mathbf{j}) + \mathbf{C}$$

## DEFINITE AND INDEFINITE INTEGRALS OF VECTOR-VALUED FUNCTIONS

**Example** Find  $\mathbf{r}(t)$  given that  $\mathbf{r}'(t) = \langle 3, 2t \rangle$  and  $\mathbf{r}(1) = \langle 2, 5 \rangle$ .

$$\mathbf{r}(t) = \int \mathbf{r}'(t) dt = \int \langle 3, 2t \rangle dt = \langle 3t, t^2 \rangle + \mathbf{C}$$

But  $\mathbf{r}(1) = \langle 2, 5 \rangle$

$$\langle 3, 1 \rangle + \mathbf{C} = \langle 2, 5 \rangle$$

$$\mathbf{C} = \langle -1, 4 \rangle$$

So  $\mathbf{r}(t) = \langle 3t, t^2 \rangle + \langle -1, 4 \rangle$

$$\mathbf{r}(t) = \langle 3t - 1, t^2 + 4 \rangle$$



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VECTOR-VALUED FUNCTIONS

Section: [12.3]

CHANGE OF PARAMETER; ARC LENGTH

## SMOOTH PARAMETRIZATIONS

- We will say that a curve represented by  $\mathbf{r}(t)$  is *smoothly parametrized* by  $\mathbf{r}(t)$ , or that  $\mathbf{r}(t)$  is a smooth function of  $t$  if:
  - ✓  $\mathbf{r}'(t)$  is continuous, and
  - ✓  $\mathbf{r}'(t) \neq \mathbf{0}$  for any allowable value of  $t$ .
- Geometrically, this means that a smoothly parametrized curve can have no abrupt (مفاجئ) changes in direction as the parameter increases.

## SMOOTH PARAMETRIZATIONS

**Example** Determine whether the following vector-valued functions are smooth.

1  $\mathbf{r}(t) = a \cos t \mathbf{i} + a \sin t \mathbf{j} + ct \mathbf{k} \quad a > 0, c > 0$

$$\mathbf{r}'(t) = -a \sin t \mathbf{i} + a \cos t \mathbf{j} + c \mathbf{k}$$

- ✓ The components are continuous functions, and
- ✓ there is no value of  $t$  for which all three of them are zero.
- ✓ So  $\mathbf{r}(t)$  is a smooth function.

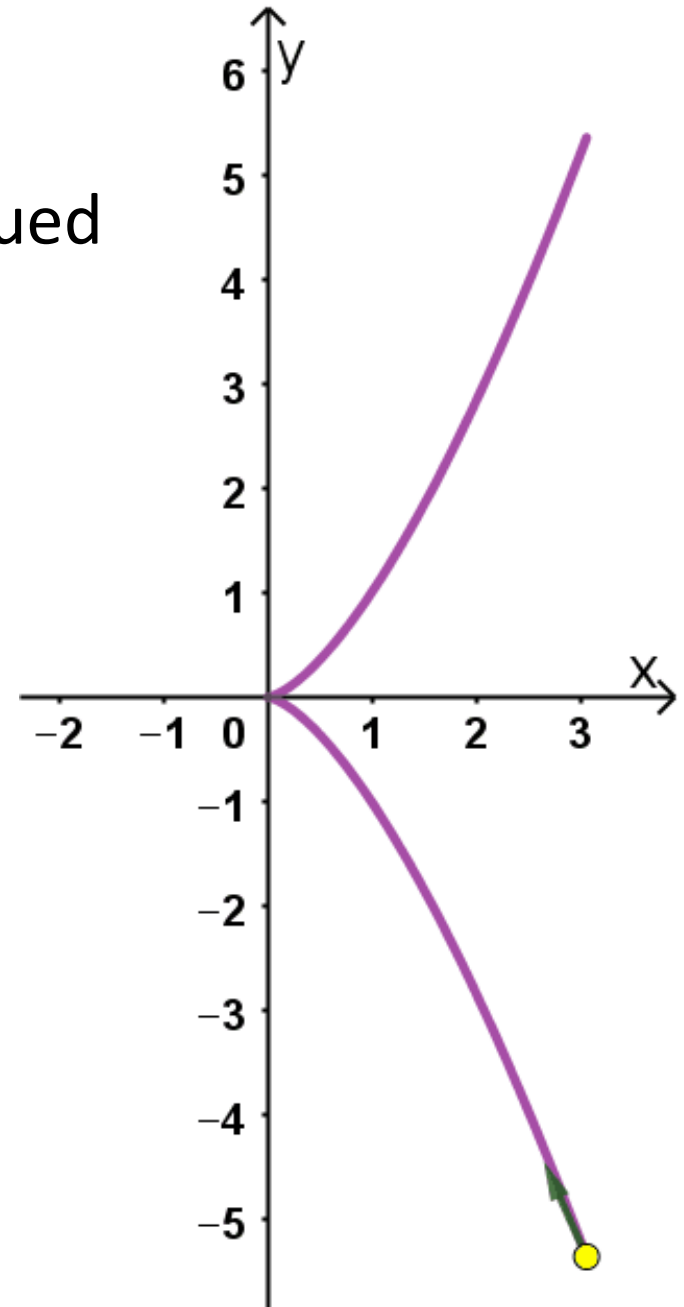
## SMOOTH PARAMETRIZATIONS

**Example** Determine whether the following vector-valued functions are smooth.

2  $\mathbf{r}(t) = t^2\mathbf{i} + t^3\mathbf{j}$

$$\mathbf{r}'(t) = 2t\mathbf{i} + 3t^2\mathbf{j}$$

- ✓ The components are continuous functions, and
- ✓ they are both equal to zero if  $t = 0$ .
- ✓ So,  $\mathbf{r}(t)$  is **NOT** a smooth function.



## ARC LENGTH FROM THE VECTOR VIEWPOINT

If  $C$  is the graph of a smooth vector-valued function  $\mathbf{r}(t)$ , then its **arc length**  $\ell$  from  $t = a$  to  $t = b$  is

$$\ell = \int_a^b \left\| \frac{d\mathbf{r}}{dt} \right\| dt = \int_a^b \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2} dt$$

**Example** Find the arc length of that portion of the circular helix  $\mathbf{r}(t) = \langle \cos t, \sin t, t \rangle$  from  $t = 0$  to  $t = \pi$ .

## ARC LENGTH FROM THE VECTOR VIEWPOINT

$$\ell = \int_a^b \left\| \frac{d\mathbf{r}}{dt} \right\| dt = \int_a^b \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2} dt$$

**Example** Find the arc length of that portion of the circular helix  $\mathbf{r}(t) = \langle \cos t, \sin t, t \rangle$  from  $t = 0$  to  $t = \pi$ .

$$\mathbf{r}'(t) = \langle -\sin t, \cos t, 1 \rangle$$

$$\begin{aligned} \|\mathbf{r}'(t)\| &= \sqrt{(-\sin t)^2 + \cos^2 t + 1} \\ &= \sqrt{2} \end{aligned}$$

$$\begin{aligned} \ell &= \int_0^\pi \|\mathbf{r}'(t)\| dt \\ &= \int_0^\pi \sqrt{2} dt \\ &= \sqrt{2} \pi \end{aligned}$$

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VECTOR-VALUED FUNCTIONS

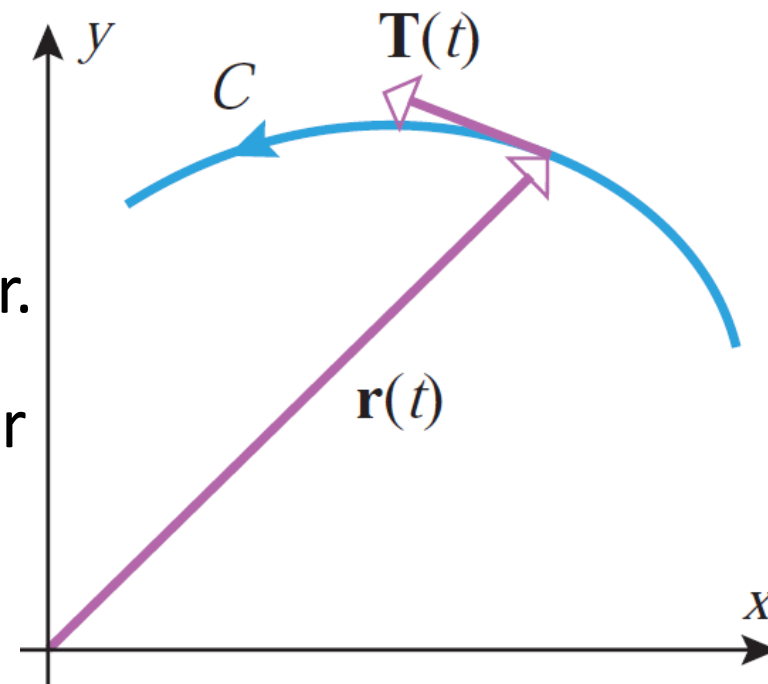
Section: [12.4]

UNIT TANGENT, NORMAL, AND BINORMAL VECTORS

## UNIT TANGENT VECTORS

- Recall that if  $C$  is the graph of a *smooth* vector-valued function  $\mathbf{r}(t)$ , then the vector  $\mathbf{r}'(t)$  is:
  - ✓ nonzero, tangent to  $C$ , and
  - ✓ points in the direction of increasing parameter.
- Thus, by normalizing  $\mathbf{r}'(t)$  we obtain a unit vector

$$\mathbf{T}(t) = \frac{\mathbf{r}'(t)}{\|\mathbf{r}'(t)\|}$$



that is tangent to  $C$  and points in the direction of increasing parameter.

- We call  $\mathbf{T}(t)$  the **unit tangent vector to  $C$  at  $t$** .



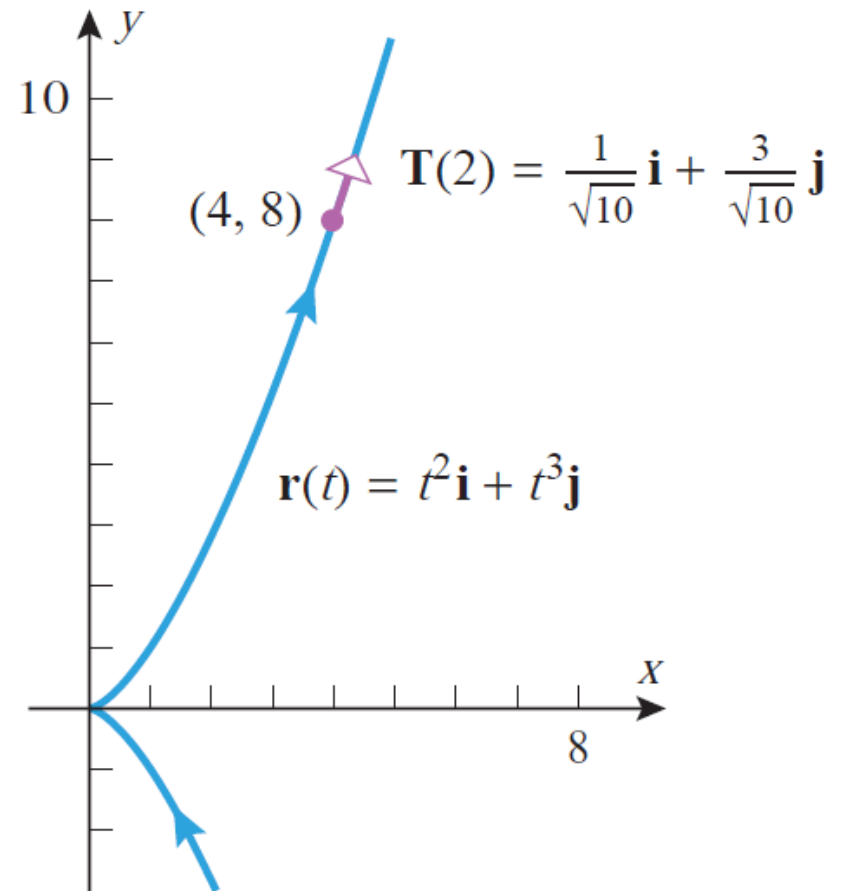
## UNIT TANGENT VECTORS

**Example** Find the unit tangent vector to the graph of  $\mathbf{r}(t) = t^2\mathbf{i} + t^3\mathbf{j}$  at the point where  $t = 2$ .

$$\mathbf{r}'(t) = 2t\mathbf{i} + 3t^2\mathbf{j}$$

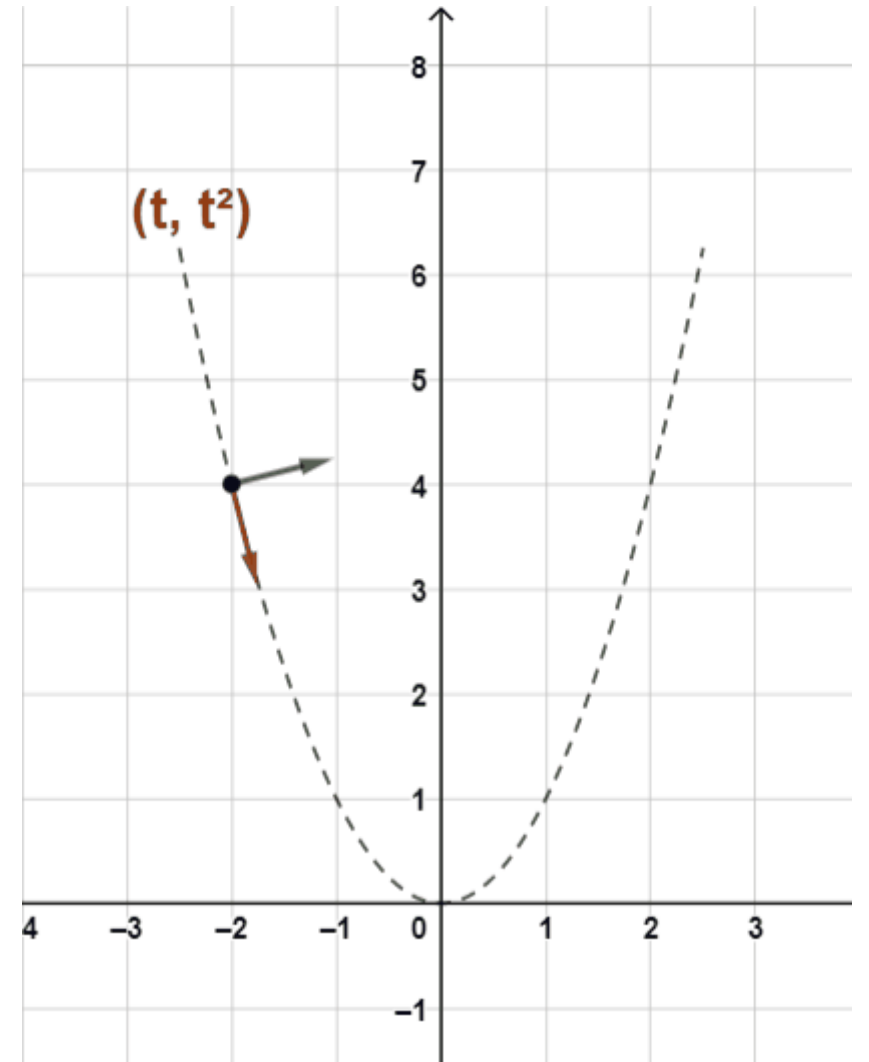
$$\mathbf{r}'(2) = 4\mathbf{i} + 12\mathbf{j}$$

$$\begin{aligned}\mathbf{T}(2) &= \frac{\mathbf{r}'(2)}{\|\mathbf{r}'(2)\|} \\ &= \frac{4\mathbf{i} + 12\mathbf{j}}{\sqrt{160}} = \frac{1}{\sqrt{10}}\mathbf{i} + \frac{3}{\sqrt{10}}\mathbf{j}\end{aligned}$$



## UNIT NORMAL VECTORS

- Recall if  $\|\mathbf{r}(t)\| = c$ , then  $\mathbf{r}(t)$  and  $\mathbf{r}'(t)$  are orthogonal vectors.
- $\mathbf{T}(t)$  has constant norm 1, so  $\mathbf{T}(t)$  and  $\mathbf{T}'(t)$  are orthogonal vectors.
- This implies that  $\mathbf{T}'(t)$  is perpendicular to the tangent line to  $C$  at  $t$ , so we say that  $\mathbf{T}'(t)$  is *normal* to  $C$  at  $t$ .

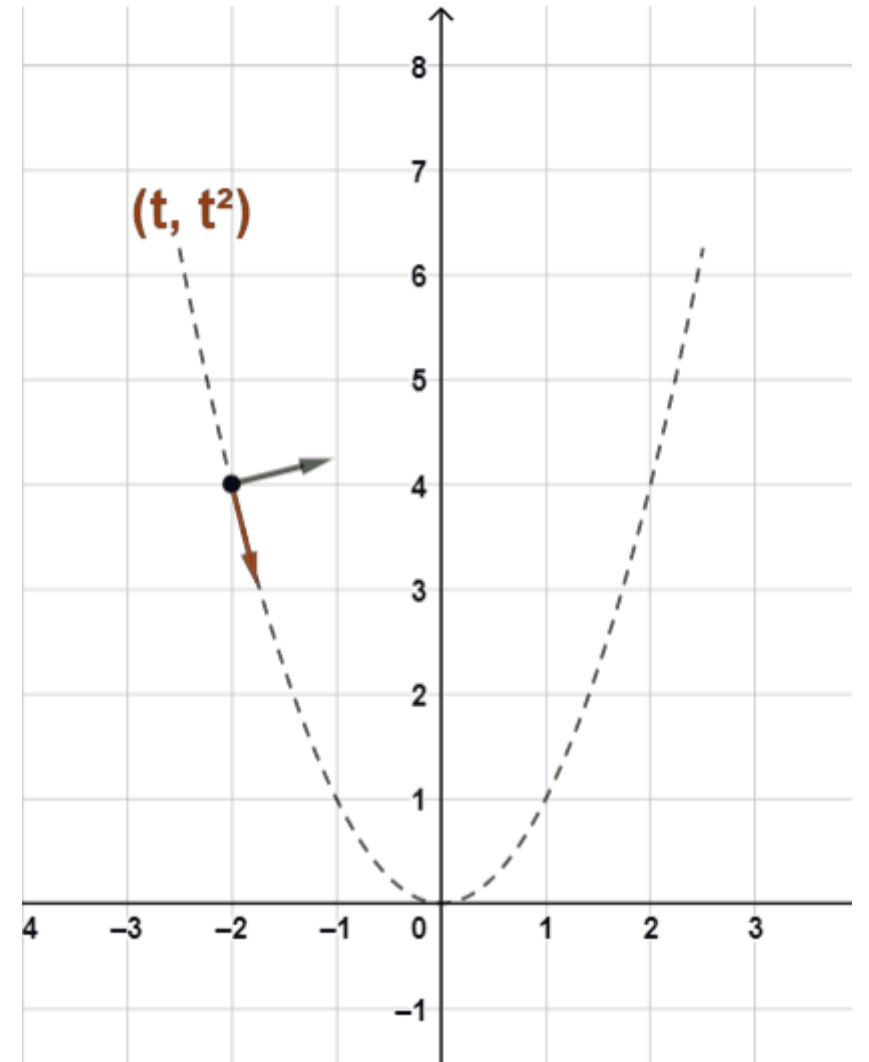


## UNIT NORMAL VECTORS

- It follows that if  $\mathbf{T}'(t) \neq \mathbf{0}$ , and if we normalize  $\mathbf{T}'(t)$ , then we obtain a unit vector

$$\mathbf{N}(t) = \frac{\mathbf{T}'(t)}{\|\mathbf{T}'(t)\|}$$

that is normal to  $C$  and points in the same direction as  $\mathbf{T}'(t)$ .



## UNIT NORMAL VECTORS

- We call  $\mathbf{N}(t)$  the *principal unit normal vector to  $C$  at  $t$* , or more simply, the *unit normal vector*.
- Observe that the unit normal vector is defined only at points where  $\mathbf{T}'(t) \neq \mathbf{0}$ . Unless stated otherwise, we will assume that this condition is satisfied.
- In particular, this excludes straight lines.

## UNIT NORMAL VECTORS

**Example** Find  $\mathbf{T}(t)$  and  $\mathbf{N}(t)$  for the circular helix  $\mathbf{r}(t) = \langle 3 \cos t, 3 \sin t, 4t \rangle$ .

$$\mathbf{r}'(t) = \langle -3 \sin t, 3 \cos t, 4 \rangle$$

$$\|\mathbf{r}'(t)\| = \sqrt{9 \sin^2 t + 9 \cos^2 t + 16} = 5$$

$$\mathbf{T}(t) = \frac{\langle -3 \sin t, 3 \cos t, 4 \rangle}{5} = \left\langle \frac{-3}{5} \sin t, \frac{3}{5} \cos t, \frac{4}{5} \right\rangle$$

## UNIT NORMAL VECTORS

**Example** Find  $\mathbf{T}(t)$  and  $\mathbf{N}(t)$  for the circular helix  $\mathbf{r}(t) = \langle 3 \cos t, 3 \sin t, 4t \rangle$ .

$$\mathbf{T}(t) = \frac{\langle -3 \sin t, 3 \cos t, 4 \rangle}{5} = \left\langle \frac{-3}{5} \sin t, \frac{3}{5} \cos t, \frac{4}{5} \right\rangle$$

$$\mathbf{T}'(t) = \left\langle \frac{-3}{5} \cos t, \frac{-3}{5} \sin t, 0 \right\rangle$$

$$\|\mathbf{T}'(t)\| = \sqrt{\frac{9}{25} \cos^2 t + \frac{9}{25} \sin^2 t + 0} = \frac{3}{5}$$

## UNIT NORMAL VECTORS

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## UNIT NORMAL VECTORS

**Example** Find  $\mathbf{T}(t)$  and  $\mathbf{N}(t)$  for  $\mathbf{r}(t) = \left\langle \frac{1}{2}t^2, \frac{1}{3}t^3 \right\rangle$  at  $t = 1$ .

$$\mathbf{r}'(t) = \langle t, t^2 \rangle \quad \mathbf{r}'(1) = \langle 1, 1 \rangle$$

$$\mathbf{T}(1) = \frac{\mathbf{r}'(1)}{\|\mathbf{r}'(1)\|} = \frac{\langle 1, 1 \rangle}{\sqrt{2}} = \left\langle \frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}} \right\rangle$$

$$\mathbf{T}(t) = \frac{\mathbf{r}'(t)}{\|\mathbf{r}'(t)\|} = \frac{1}{\sqrt{t^2 + t^4}} \langle t, t^2 \rangle = (t^2 + t^4)^{-1/2} \langle t, t^2 \rangle$$

$$\mathbf{T}'(t) = (t^2 + t^4)^{-1/2} \langle 1, 2t \rangle - \frac{1}{2} (2t + 4t^3) (t^2 + t^4)^{-3/2} \langle t, t^2 \rangle$$



## UNIT NORMAL VECTORS

**Example** Find  $\mathbf{T}(t)$  and  $\mathbf{N}(t)$  for  $\mathbf{r}(t) = \left\langle \frac{1}{2}t^2, \frac{1}{3}t^3 \right\rangle$  at  $t = 1$ .

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$$\mathbf{T}'(1) = \frac{\langle 1, 2 \rangle}{\sqrt{2}} - \frac{3\langle 1, 1 \rangle}{2\sqrt{2}} = \left\langle \frac{-1}{2\sqrt{2}}, \frac{1}{2\sqrt{2}} \right\rangle$$

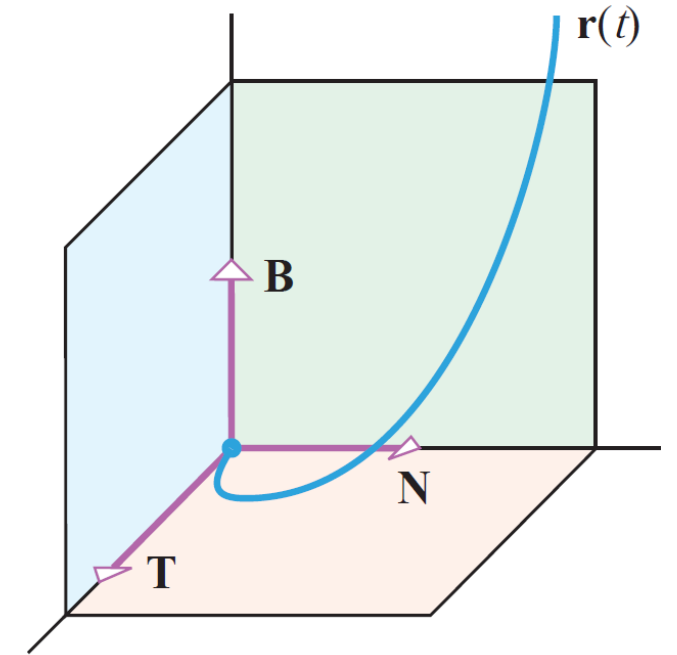
$$\|\mathbf{T}'(1)\| = \sqrt{\left(\frac{-1}{2\sqrt{2}}\right)^2 + \left(\frac{1}{2\sqrt{2}}\right)^2} = \frac{1}{2}$$

$$\mathbf{N}(1) = \frac{\mathbf{T}'(1)}{\|\mathbf{T}'(1)\|} = \left\langle \frac{-1}{\sqrt{2}}, \frac{1}{\sqrt{2}} \right\rangle$$

## BINORMAL VECTORS IN 3 – SPACE

If  $C$  is the graph of a vector-valued function  $\mathbf{r}(t)$  in 3 – space, then we define the *binormal vector* to  $C$  at  $t$  to be

$$\mathbf{B}(t) = \mathbf{T}(t) \times \mathbf{N}(t)$$



- It follows from properties of the cross product that  $\mathbf{B}(t)$  is orthogonal to both  $\mathbf{T}(t)$  and  $\mathbf{N}(t)$  and is oriented relative to  $\mathbf{T}(t)$  and  $\mathbf{N}(t)$  by the right-hand rule.
- $\mathbf{B}(t)$  is unit vector !!.

$$\|\mathbf{B}(t)\| = \|\mathbf{T}(t) \times \mathbf{N}(t)\| = \|\mathbf{T}(t)\| \|\mathbf{N}(t)\| \sin \frac{\pi}{2} = 1$$

## BINORMAL VECTORS IN 3 –SPACE

Note that  $\mathbf{T}(t)$ ,  $\mathbf{N}(t)$ ,  $\mathbf{B}(t)$  are three *mutually orthogonal unit vectors*.

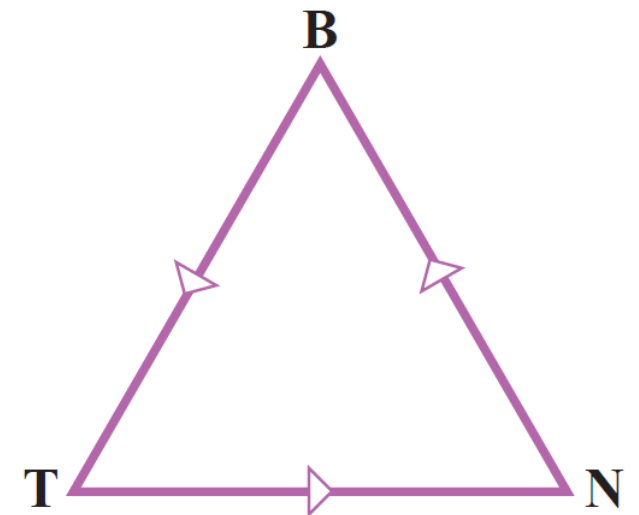
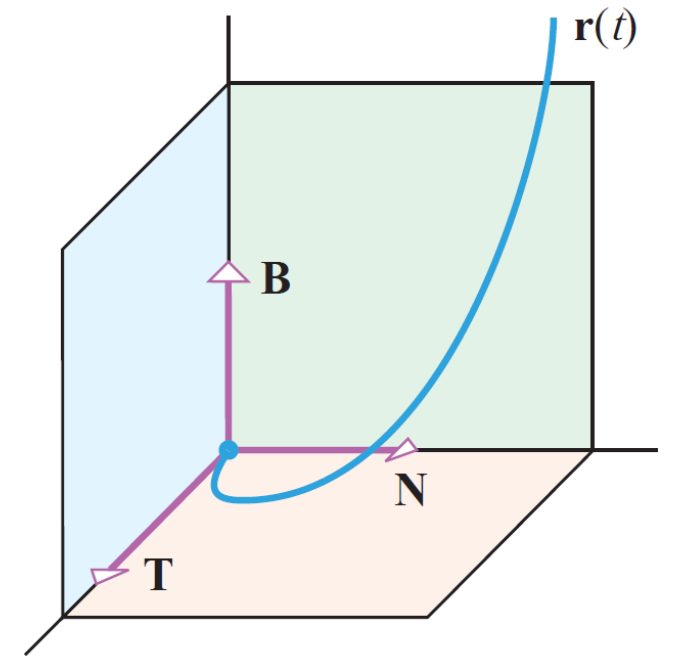
$$\mathbf{B}(t) = \mathbf{T}(t) \times \mathbf{N}(t)$$

$$\mathbf{N}(t) = \mathbf{B}(t) \times \mathbf{T}(t)$$

$$\mathbf{T}(t) = \mathbf{N}(t) \times \mathbf{B}(t)$$

The binormal  $\mathbf{B}(t)$  can be expressed directly in terms of  $\mathbf{r}(t)$  as:

$$\mathbf{B}(t) = \frac{\mathbf{r}'(t) \times \mathbf{r}''(t)}{\|\mathbf{r}'(t) \times \mathbf{r}''(t)\|}$$



## BINORMAL VECTORS IN 3 –SPACE

**Example** Find  $\mathbf{B}(t)$  for the circular helix  $\mathbf{r}(t) = \langle 3 \cos t, 3 \sin t, 4t \rangle$ .

$$\mathbf{T}(t) = \left\langle \frac{-3}{5} \sin t, \frac{3}{5} \cos t, \frac{4}{5} \right\rangle \quad \mathbf{N}(t) = \langle -\cos t, -\sin t, 0 \rangle$$

$$\begin{aligned} \mathbf{B}(t) = \mathbf{T}(t) \times \mathbf{N}(t) &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ -\frac{3}{5} \sin t & \frac{3}{5} \cos t & \frac{4}{5} \\ -\cos t & -\sin t & 0 \end{vmatrix} \\ &= \left\langle \frac{4}{5} \sin t, \frac{-4}{5} \cos t, \frac{3}{5} \right\rangle \end{aligned}$$

## BINORMAL VECTORS IN 3 –SPACE

**Example** Find  $\mathbf{B}(t)$  for the circular helix  $\mathbf{r}(t) = \langle 3 \cos t, 3 \sin t, 4t \rangle$ .

$$\mathbf{r}'(t) = \langle -3 \sin t, 3 \cos t, 4 \rangle$$

$$\mathbf{r}''(t) = \langle -3 \cos t, -3 \sin t, 0 \rangle$$

$$\mathbf{r}'(t) \times \mathbf{r}''(t) = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ -3 \sin t & 3 \cos t & 4 \\ -3 \cos t & -3 \sin t & 0 \end{vmatrix} = \langle 12 \sin t, -12 \cos t, 9 \rangle$$

$$\begin{aligned} \mathbf{B}(t) &= \frac{\mathbf{r}'(t) \times \mathbf{r}''(t)}{\|\mathbf{r}'(t) \times \mathbf{r}''(t)\|} = \frac{\langle 12 \sin t, -12 \cos t, 9 \rangle}{25} \\ &= \left\langle \frac{4}{5} \sin t, -\frac{4}{5} \cos t, \frac{3}{5} \right\rangle \end{aligned}$$

Course: Calculus (3)

Chapter: [12]

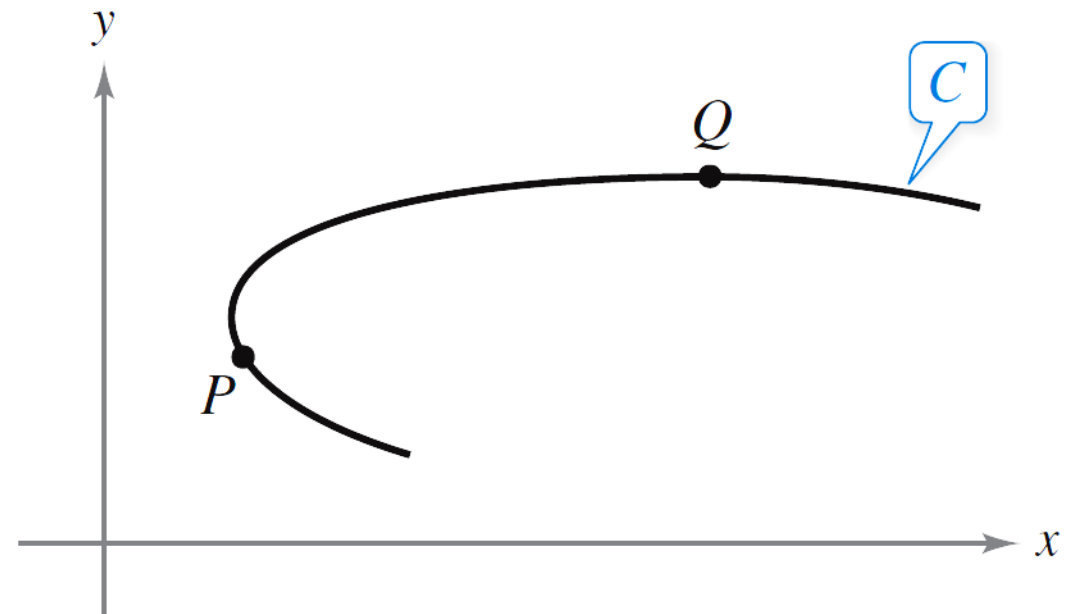
VECTOR-VALUED FUNCTIONS

Section: [12.5]

CURVATURE

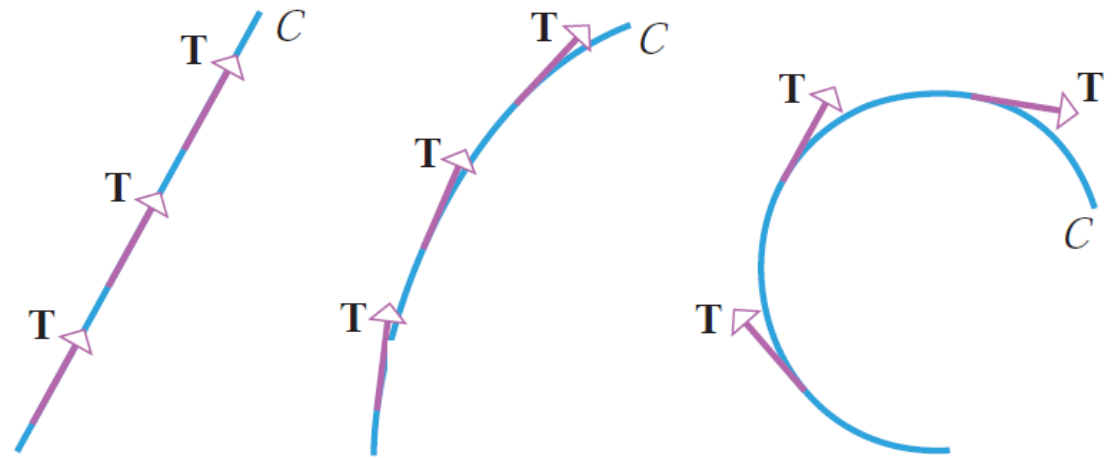
## DEFINITION OF CURVATURE

- We will consider the problem of obtaining a *numerical measure of how sharply a curve bends*.
- For instance, in the figure, the curve bends more sharply at P than at Q and you can say that the curvature is greater at P than at Q.



## DEFINITION OF CURVATURE

You can calculate curvature by calculating the magnitude of the rate of change of the unit tangent vector  $\mathbf{T}$  with respect to the arc length  $s$ .



- If  $C$  is a *straight line (no bend)*, then the direction of  $\mathbf{T}$  remains constant.
- If  $C$  *bends slightly*, then  $\mathbf{T}$  undergoes a gradual change of direction.
- If  $C$  *bends sharply*, then  $\mathbf{T}$  undergoes a rapid change of direction.



## DEFINITION OF CURVATURE

If  $\mathbf{r}(t)$  is a smooth vector-valued function, then for each value of  $t$  at which  $\mathbf{T}'(t)$  and  $\mathbf{r}''(t)$  exist, the curvature  $\kappa$  can be expressed as

$$\kappa(t) = \frac{\|\mathbf{T}'(t)\|}{\|\mathbf{r}'(t)\|} = \frac{\|\mathbf{r}'(t) \times \mathbf{r}''(t)\|}{\|\mathbf{r}'(t)\|^3}$$

**Example** Show that the curvature of a circle of radius  $R$  is  $\kappa = \frac{1}{R}$ .

1  $\kappa(t) = \frac{\|\mathbf{T}'(t)\|}{\|\mathbf{r}'(t)\|}$

## DEFINITION OF CURVATURE

**Example** Show that the curvature of a circle of radius  $R$  is  $\kappa = \frac{1}{R}$ .

$$\textcircled{1} \quad \kappa(t) = \frac{\|\mathbf{T}'(t)\|}{\|\mathbf{r}'(t)\|} \quad \mathbf{r}(t) = R \cos t \mathbf{i} + R \sin t \mathbf{j} \quad t \in [0, 2\pi]$$

$$\mathbf{r}'(t) = -R \sin t \mathbf{i} + R \cos t \mathbf{j}$$

$$\mathbf{T}(t) = \frac{\mathbf{r}'(t)}{\|\mathbf{r}'(t)\|} = \frac{\langle -R \sin t, R \cos t \rangle}{\sqrt{(-R \sin t)^2 + (R \cos t)^2}} = \langle -\sin t, \cos t \rangle$$

$$\mathbf{T}'(t) = \langle -\cos t, -\sin t \rangle$$

$$\kappa(t) = \frac{\sqrt{(-\cos t)^2 + (-\sin t)^2}}{\sqrt{(-R \sin t)^2 + (R \cos t)^2}} = \frac{1}{R}$$

## DEFINITION OF CURVATURE

**Example** Show that the curvature of a circle of radius  $R$  is  $\kappa = \frac{1}{R}$ .

$$2 \quad \kappa(t) = \frac{\|\mathbf{r}'(t) \times \mathbf{r}''(t)\|}{\|\mathbf{r}'(t)\|^3} \quad \mathbf{r}(t) = R \cos t \mathbf{i} + R \sin t \mathbf{j} + 0\mathbf{k} \quad t \in [0, 2\pi]$$

$$\mathbf{r}'(t) = -R \sin t \mathbf{i} + R \cos t \mathbf{j} + 0\mathbf{k}$$

$$\mathbf{r}''(t) = -R \cos t \mathbf{i} - R \sin t \mathbf{j} + 0\mathbf{k}$$

$$\mathbf{r}'(t) \times \mathbf{r}''(t) = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ -R \sin t & R \cos t & 0 \\ -R \cos t & -R \sin t & 0 \end{vmatrix} = R^2 \mathbf{k}$$

$$\|\mathbf{r}'(t) \times \mathbf{r}''(t)\| = R^2$$

$$\|\mathbf{r}'(t)\| = R$$

$$\kappa(t) = \frac{R^2}{R^3} = \frac{1}{R}$$