



Dept. of Computer Engineering
Second Exam, Second Semester: 2006/2007

Course Title: Real-Time Computer Control System	Date: 22/5/2007
Course No: (630581)	Time Allowed: 1 Hour
Lecturer: Dr. Mohammed Mahdi	No. of Pages: 1

Question 1:

(10 Marks)

Objectives:

This question is about difference equations, Jury test, and computer simulation.

Consider the system described by the following difference equation: -

$$y(k) - 0.6y(k-1) - 0.81y(k-2) + 0.67y(k-3) - 0.12y(k-4) = x(k)$$

It is required to: -

1. Determine the absolute stability, then comment your result. (3 Marks)
2. Write the software program segment to simulate $y(k)$. (3 Marks)
3. Draw a representative block diagram. (2 Marks)
4. Is the system realizable? Why? (2 Marks)

Question 2:

(10 Marks)

Objectives:

This question is about the z-inverse and digital PID controller.

A) Find $E(0)$ and $E(5)$ for $E(z) = 1 \setminus (z - 0.5)(z - 0.2)$ (2 Marks)

B) Given $G(s) = 1 \setminus (s + 0.2)(s + 0.5)$ it is required to: -

- 1- Find the suitable sampling rate for RTCCS. (2 Marks)
- 2- Find the suitable PID combination. Why? (2 Marks)
- 3- Write down the velocity form equation for your PID combination choice. (2 Marks)
- 4- Which is better to use velocity or positional PID form. Why? (2 Marks)