



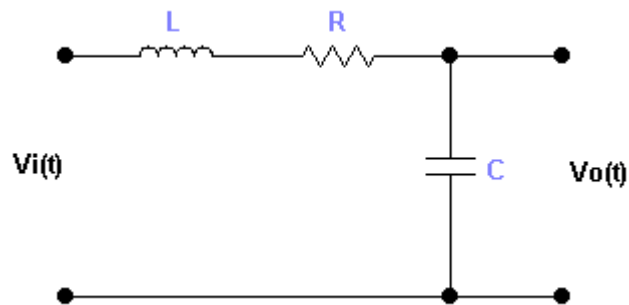
Course Title: Control Systems – sec. 1	Date: 2/6/2019
Course No: (610414+640344)	Time Allowed: 2 hours
Lecturer: Dr. Mohammed Mahdi	No. of Pages: 2

Question 1:

(25 Marks)

Objectives: This question is about system modeling.

Given the following RLC circuit: -



It is required to evaluate: -

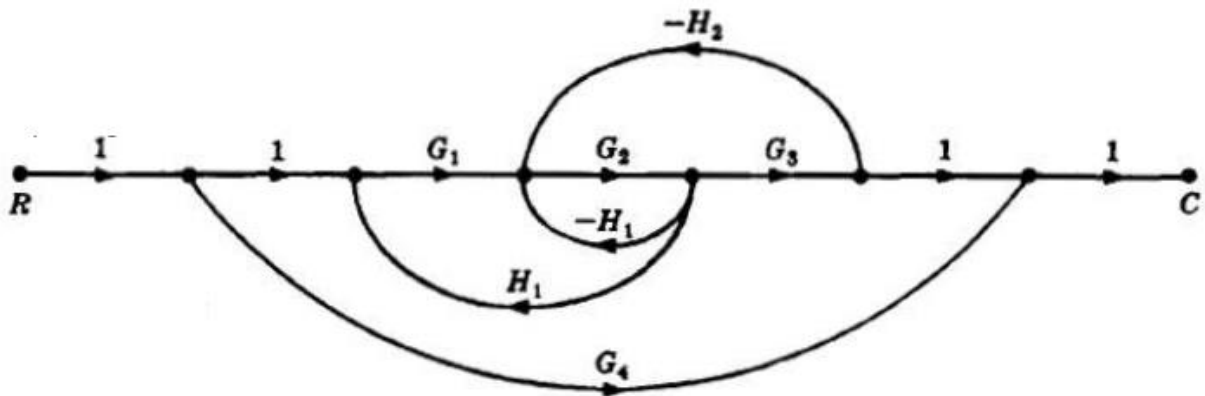
1. Transfer function $\frac{Vo(s)}{Vi(s)}$. (10 marks)
2. Show the possible kind of system output responses. (10 marks)
3. Find system parameters ω_n, ζ, k . (5 marks)

Question 2:

(25 Marks)

Objectives: This question is about Mason’s Gain Formula and time response specifications.

- A) Given the following SFG, it is required to apply Mason’s Gain Formula to obtain transfer function $C(s) / R(s)$. (15 marks)



B) Derive the general first order system time response for unit step change in input

$$\frac{Y(s)}{R(s)} = \frac{k}{\tau s + 1}. \text{ Then find } \mathbf{y(0)}, \mathbf{y(\tau)}, \text{ and } \mathbf{y(\infty)}. \quad (10 \text{ marks})$$

Question 3:

(25 Marks)

Objectives: This question is about absolute stability.

Why do the absolute stability check deal with the characteristics equation?. Then apply **two methods** to check the absolute stability of the following characteristic equation: -

$$\mathbf{P(s) = s^4 + 4 = 0}$$

Question 4:

(25 Marks)

Objectives: This question is about controller design.

Given the open loop transfer function $\mathbf{G(s) = \frac{5}{(s+20)}}$. It is required to design **PI**

controller so that the desired closed loop poles are located at **s = - 10 and s = - 20**. Then check your design result.