Solutions of Equations in One Variable

Secant & Regula Falsi Methods

Numerical Analysis (9th Edition) R L Burden & J D Faires

> Beamer Presentation Slides prepared by John Carroll Dublin City University

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3 The Method of False Position (Regula Falsi)

Rationale for the Secant Method

Problems with Newton's Method

Numerical Analysis (Chapter 2)

Secant & Regula Falsi Methods

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Rationale for the Secant Method

Problems with Newton's Method

 Newton's method is an extremely powerful technique, but it has a major weakness: the need to know the value of the derivative of f at each approximation.

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Rationale for the Secant Method

Problems with Newton's Method

- Newton's method is an extremely powerful technique, but it has a major weakness: the need to know the value of the derivative of f at each approximation.
- Frequently, f'(x) is far more difficult and needs more arithmetic operations to calculate than f(x).

$$f'(p_{n-1}) = \lim_{x \to p_{n-1}} \frac{f(x) - f(p_{n-1})}{x - p_{n-1}}.$$

Circumvent the Derivative Evaluation

Numerical Analysis (Chapter 2)

$$f'(p_{n-1}) = \lim_{x \to p_{n-1}} \frac{f(x) - f(p_{n-1})}{x - p_{n-1}}$$

Circumvent the Derivative Evaluation

If p_{n-2} is close to p_{n-1} , then

$$f'(p_{n-1}) \approx \frac{f(p_{n-2}) - f(p_{n-1})}{p_{n-2} - p_{n-1}} = \frac{f(p_{n-1}) - f(p_{n-2})}{p_{n-1} - p_{n-2}}$$

Numerical Analysis (Chapter 2)

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Using this approximation for $f'(p_{n-1})$ in Newton's formula gives

$$p_n = p_{n-1} - \frac{f(p_{n-1})(p_{n-1} - p_{n-2})}{f(p_{n-1}) - f(p_{n-2})}$$

Numerical Analysis (Chapter 2)

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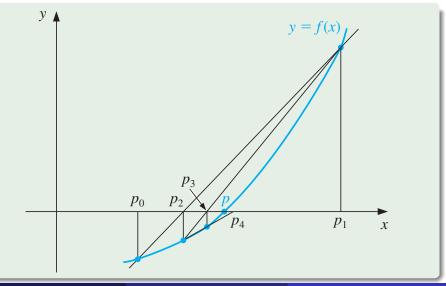
$$p_n = p_{n-1} - \frac{f(p_{n-1})(p_{n-1} - p_{n-2})}{f(p_{n-1}) - f(p_{n-2})}$$

This technique is called the Secant method

Numerical Analysis (Chapter 2)

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Secant Method: Using Successive Secants



Numerical Analysis (Chapter 2)

$$p_n = p_{n-1} - \frac{f(p_{n-1})(p_{n-1} - p_{n-2})}{f(p_{n-1}) - f(p_{n-2})}$$

Procedure

Numerical Analysis (Chapter 2)

Secant & Regula Falsi Methods

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Procedure

Starting with the two initial approximations p₀ and p₁, the approximation p₂ is the *x*-intercept of the line joining (p₀, f(p₀)) and (p₁, f(p₁)).

$$p_n = p_{n-1} - \frac{f(p_{n-1})(p_{n-1} - p_{n-2})}{f(p_{n-1}) - f(p_{n-2})}$$

Procedure

- Starting with the two initial approximations p₀ and p₁, the approximation p₂ is the *x*-intercept of the line joining (p₀, f(p₀)) and (p₁, f(p₁)).
- The approximation p₃ is the *x*-intercept of the line joining (p₁, f(p₁)) and (p₂, f(p₂)), and so on.

$$p_n = p_{n-1} - \frac{f(p_{n-1})(p_{n-1} - p_{n-2})}{f(p_{n-1}) - f(p_{n-2})}$$

Procedure

- Starting with the two initial approximations p₀ and p₁, the approximation p₂ is the *x*-intercept of the line joining (p₀, f(p₀)) and (p₁, f(p₁)).
- The approximation p₃ is the *x*-intercept of the line joining (p₁, f(p₁)) and (p₂, f(p₂)), and so on.
- Note that only one function evaluation is needed per step for the Secant method after p₂ has been determined.

$$p_n = p_{n-1} - \frac{f(p_{n-1})(p_{n-1} - p_{n-2})}{f(p_{n-1}) - f(p_{n-2})}$$

Procedure

- Starting with the two initial approximations p₀ and p₁, the approximation p₂ is the *x*-intercept of the line joining (p₀, f(p₀)) and (p₁, f(p₁)).
- The approximation p₃ is the *x*-intercept of the line joining (p₁, f(p₁)) and (p₂, f(p₂)), and so on.
- Note that only one function evaluation is needed per step for the Secant method after p₂ has been determined.
- In contrast, each step of Newton's method requires an evaluation of both the function and its derivative.

Secant & Regula Falsi Methods

To find a solution to f(x) = 0 given initial approximations p_0 and p_1 ; tolerance *TOL*; maximum number of iterations N_0 .

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1 Set
$$i = 2, q_0 = f(p_0), q_1 = f(p_1)$$

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- 1 Set $i = 2, q_0 = f(p_0), q_1 = f(p_1)$
- 2 While $i \leq N_0$ do Steps 3–6:
 - 3 Set $p = p_1 q_1(p_1 p_0)/(q_1 q_0)$. (Compute p_i)

To find a solution to f(x) = 0 given initial approximations p_0 and p_1 ; tolerance *TOL*; maximum number of iterations N_0 .

- 1 Set $i = 2, q_0 = f(p_0), q_1 = f(p_1)$
- 2 While $i \leq N_0$ do Steps 3–6:

3 Set
$$p = p_1 - q_1(p_1 - p_0)/(q_1 - q_0)$$
. (Compute p_i)

4 If $|p - p_1| < TOL$ then OUTPUT (*p*); (*The procedure was successful.*) STOP

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5 Set i = i + 1

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OUTPUT (p); (*The procedure was successful.*) STOP
5 Set $i = i + 1$
6 Set $p_0 = p_1$; (*Update* p_0, q_0, p_1, q_1)
 $q_0 = q_1; p_1 = p; q_1 = f(p)$

To find a solution to f(x) = 0 given initial approximations p_0 and p_1 ; tolerance *TOL*; maximum number of iterations N_0 .

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5 Set $i = i + 1$
6 Set $p_0 = p_1$; (*Update* p_0, q_0, p_1, q_1)
 $q_0 = q_1; p_1 = p; q_1 = f(p)$

7 OUTPUT ('The method failed after N_0 iterations, $N_0 =$ ', N_0); (*The procedure was unsuccessful*) STOP

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The Method of False Position (Regula Falsi)

Example: $f(x) = \cos x - x$

Use the Secant method to find a solution to $x = \cos x$, and compare the approximations with those given by Newton's method with $p_0 = \pi/4$.

Formula for the Secant Method

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We need two initial approximations. Suppose we use $p_0 = 0.5$ and $p_1 = \pi/4$.

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Example: $f(x) = \cos x - x$

Use the Secant method to find a solution to $x = \cos x$, and compare the approximations with those given by Newton's method with $p_0 = \pi/4$.

Formula for the Secant Method

We need two initial approximations. Suppose we use $p_0 = 0.5$ and $p_1 = \pi/4$. Succeeding approximations are generated by the formula

$$p_n = p_{n-1} - \frac{(p_{n-1} - p_{n-2})(\cos p_{n-1} - p_{n-1})}{(\cos p_{n-1} - p_{n-1}) - (\cos p_{n-2} - p_{n-2})}, \text{ for } n \ge 2.$$

Newton's Method for $f(x) = \cos(x) - x$, $p_0 = \frac{\pi}{4}$

n	p_{n-1}	$f(p_{n-1})$	$f'(p_{n-1})$	<i>p</i> _n	$ p_n - p_{n-1} $
1	0.78539816	-0.078291	-1.707107	0.73953613	0.04586203
2	0.73953613	-0.000755	-1.673945	0.73908518	0.00045096
3	0.73908518	-0.000000	-1.673612	0.73908513	0.00000004
4	0.73908513	-0.000000	-1.673612	0.73908513	0.0000000

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Newton's Method for $f(x) = \cos(x) - x$, $p_0 = \frac{\pi}{4}$

n	p_{n-1}	$f(p_{n-1})$	$f'(p_{n-1})$	p _n	$ p_n - p_{n-1} $
1	0.78539816	-0.078291	-1.707107	0.73953613	0.04586203
2	0.73953613	-0.000755	-1.673945	0.73908518	0.00045096
3	0.73908518	-0.000000	-1.673612	0.73908513	0.00000004
4	0.73908513	-0.000000	-1.673612	0.73908513	0.00000000

• An excellent approximation is obtained with n = 3.

Numerical Analysis (Chapter 2)

Newton's Method for $f(x) = \cos(x) - x$, $p_0 = \frac{\pi}{4}$

n	p_{n-1}	$f(p_{n-1})$	$f'(p_{n-1})$	p _n	$ p_n - p_{n-1} $
1	0.78539816	-0.078291	-1.707107	0.73953613	0.04586203
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4	0.73908513	-0.000000	-1.673612	0.73908513	0.00000000

• An excellent approximation is obtained with n = 3.

 Because of the agreement of p₃ and p₄ we could reasonably expect this result to be accurate to the places listed.

Secant Method for $f(x) = \cos(x) - x$, $p_0 = 0.5$, $p_1 = \frac{\pi}{4}$

n	<i>p</i> _{n-2}	<i>p</i> _{n-1}	p _n	$ p_n - p_{n-1} $
2	0.500000000	0.785398163	0.736384139	0.0490140246
3	0.785398163	0.736384139	0.739058139	0.0026740004
4	0.736384139	0.739058139	0.739085149	0.0000270101
5	0.739058139	0.739085149	0.739085133	0.000000161

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Secant Method for $f(x) = \cos(x) - x$, $p_0 = 0.5$, $p_1 = \frac{\pi}{4}$

n	<i>p</i> _{n-2}	<i>p</i> _{n-1}	pn	$ p_n - p_{n-1} $
2	0.500000000	0.785398163	0.736384139	0.0490140246
3	0.785398163	0.736384139	0.739058139	0.0026740004
4	0.736384139	0.739058139	0.739085149	0.0000270101
5	0.739058139	0.739085149	0.739085133	0.0000000161

 Comparing results, we see that the Secant Method approximation *p*₅ is accurate to the tenth decimal place, whereas Newton's method obtained this accuracy by *p*₃.

Secant Method for $f(x) = \cos(x) - x$, $p_0 = 0.5$, $p_1 = \frac{\pi}{4}$

n	<i>p</i> _{n-2}	<i>p</i> _{n-1}	p _n	$ p_n - p_{n-1} $
2	0.500000000	0.785398163	0.736384139	0.0490140246
3	0.785398163	0.736384139	0.739058139	0.0026740004
4	0.736384139	0.739058139	0.739085149	0.0000270101
5	0.739058139	0.739085149	0.739085133	0.0000000161

- Comparing results, we see that the Secant Method approximation *p*₅ is accurate to the tenth decimal place, whereas Newton's method obtained this accuracy by *p*₃.
- Here, the convergence of the Secant method is much faster than functional iteration but slightly slower than Newton's method.

Comparing the Secant & Newton's Methods

Secant Method for $f(x) = \cos(x) - x$, $p_0 = 0.5$, $p_1 = \frac{\pi}{4}$

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2	0.500000000	0.785398163	0.736384139	0.0490140246
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- Comparing results, we see that the Secant Method approximation *p*₅ is accurate to the tenth decimal place, whereas Newton's method obtained this accuracy by *p*₃.
- Here, the convergence of the Secant method is much faster than functional iteration but slightly slower than Newton's method.
- This is generally the case. Order of Convergence

The Secant Method

Final Remarks

Numerical Analysis (Chapter 2)

Secant & Regula Falsi Methods

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The Secant Method

Final Remarks

• The Secant method and Newton's method are often used to refine an answer obtained by another technique (such as the Bisection Method).

Numerical Analysis (Chapter 2)

Secant & Regula Falsi Methods

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The Secant Method

Final Remarks

- The Secant method and Newton's method are often used to refine an answer obtained by another technique (such as the Bisection Method).
- Both methods require good first approximations but generally give rapid acceleration.

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2 Comparing the Secant & Newton's Methods



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Bracketing a Root

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Bracketing a Root

 Unlike the Bisection Method, root bracketing is not guaranteed for either Newton's method or the Secant method.

Bracketing a Root

- Unlike the Bisection Method, root bracketing is not guaranteed for either Newton's method or the Secant method.
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Bracketing a Root

- Unlike the Bisection Method, root bracketing is not guaranteed for either Newton's method or the Secant method.
- The method of False Position (also called *Regula Falsi*) generates approximations in the same manner as the Secant method, but it includes a test to ensure that the root is always bracketed between successive iterations.
- Although it is not a method we generally recommend, it illustrates how bracketing can be incorporated.

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Construction of the Method

• First choose initial approximations p_0 and p_1 with $f(p_0) \cdot f(p_1) < 0$.

Numerical Analysis (Chapter 2)

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Construction of the Method

- First choose initial approximations p_0 and p_1 with $f(p_0) \cdot f(p_1) < 0$.
- The approximation p₂ is chosen in the same manner as in the Secant method, as the x-intercept of the line joining (p₀, f(p₀)) and (p₁, f(p₁)).

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- To decide which secant line to use to compute p₃, consider f(p₂) · f(p₁), or more correctly sgn f(p₂) · sgn f(p₁):

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- To decide which secant line to use to compute p₃, consider f(p₂) · f(p₁), or more correctly sgn f(p₂) · sgn f(p₁):
 - If sgn f(p₂) ⋅ sgn f(p₁) < 0, then p₁ and p₂ bracket a root. Choose p₃ as the *x*-intercept of the line joining (p₁, f(p₁)) and (p₂, f(p₂)).

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Construction of the Method

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- To decide which secant line to use to compute p₃, consider f(p₂) · f(p₁), or more correctly sgn f(p₂) · sgn f(p₁):
 - If sgn f(p₂) · sgn f(p₁) < 0, then p₁ and p₂ bracket a root. Choose p₃ as the *x*-intercept of the line joining (p₁, f(p₁)) and (p₂, f(p₂)).
 - If not, choose p_3 as the *x*-intercept of the line joining $(p_0, f(p_0))$ and $(p_2, f(p_2))$, and then interchange the indices on p_0 and p_1 .

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Construction of the Method (Cont'd)

Numerical Analysis (Chapter 2)

Secant & Regula Falsi Methods

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Construction of the Method (Cont'd)

 In a similar manner, once p₃ is found, the sign of f(p₃) · f(p₂) determines whether we use p₂ and p₃ or p₃ and p₁ to compute p₄.

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Construction of the Method (Cont'd)

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- In the latter case, a relabeling of p_2 and p_1 is performed.

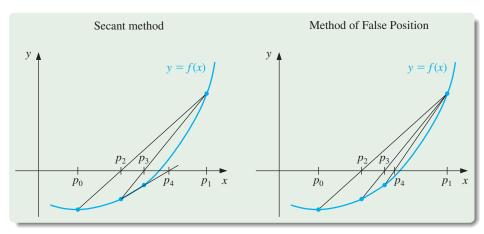
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Construction of the Method (Cont'd)

- In a similar manner, once p₃ is found, the sign of f(p₃) ⋅ f(p₂) determines whether we use p₂ and p₃ or p₃ and p₁ to compute p₄.
- In the latter case, a relabeling of p_2 and p_1 is performed.
- The relabelling ensures that the root is bracketed between successive iterations.

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Secant Method & Method of False Position



In this illustration, the first three approximations are the same for both methods, but the fourth approximations differ.

Numerical Analysis (Chapter 2)

Secant & Regula Falsi Methods

To find a solution to f(x) = 0, given the continuous function f on the interval $[p_0, p_1]$ (where $f(p_0)$ and $f(p_1)$ have opposite signs) tolerance *TOL* and maximum number of iterations N_0 .

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1 Set
$$i = 2$$
; $q_0 = f(p_0)$; $q_1 = f(p_1)$.

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To find a solution to f(x) = 0, given the continuous function f on the interval $[p_0, p_1]$ (where $f(p_0)$ and $f(p_1)$ have opposite signs) tolerance *TOL* and maximum number of iterations N_0 .

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- 2 While $i \leq N_0$ do Steps 3–7:

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- 1 Set i = 2; $q_0 = f(p_0)$; $q_1 = f(p_1)$.
- 2 While $i \leq N_0$ do Steps 3–7:
 - 3 Set $p = p_1 q_1(p_1 p_0)/(q_1 q_0)$. (Compute p_i)

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1 Set
$$i = 2$$
; $q_0 = f(p_0)$; $q_1 = f(p_1)$.

2 While $i \leq N_0$ do Steps 3–7:

3 Set
$$p = p_1 - q_1(p_1 - p_0)/(q_1 - q_0)$$
. (Compute p_i)

4 If $|p - p_1| < TOL$ then OUTPUT (*p*); (*The procedure was successful*): STOP

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3 Set
$$p = p_1 - q_1(p_1 - p_0)/(q_1 - q_0)$$
. (Compute p_i)

4 If |p - p₁| < TOL then OUTPUT (p); (*The procedure was successful*): STOP
5 Set i = i + 1; q = f(p)

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To find a solution to f(x) = 0, given the continuous function f on the interval $[p_0, p_1]$ (where $f(p_0)$ and $f(p_1)$ have opposite signs) tolerance *TOL* and maximum number of iterations N_0 .

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. (Compute p_i)

4 If
$$|p - p_1| < TOL$$
 then
OUTPUT (*p*); (*The procedure was successful*): STOP

5 Set
$$i = i + 1$$
; $q = f(p)$

6 If
$$q \cdot q_1 < 0$$
 then set $p_0 = p_1$; $q_0 = q_1$

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To find a solution to f(x) = 0, given the continuous function f on the interval $[p_0, p_1]$ (where $f(p_0)$ and $f(p_1)$ have opposite signs) tolerance *TOL* and maximum number of iterations N_0 .

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4 If
$$|p - p_1| < TOL$$
 then
OUTPUT (*p*); (*The procedure was successful*): STOP
5 Set $i = i + 1$; $q = f(p)$

6 If
$$q \cdot q_1 < 0$$
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7 Set
$$p_1 = p; q_1 = q$$

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$$i = 2$$
; $q_0 = f(p_0)$; $q_1 = f(p_1)$.

2 While $i \leq N_0$ do Steps 3–7:

3 Set
$$p = p_1 - q_1(p_1 - p_0)/(q_1 - q_0)$$
. (Compute p_i)

4 If
$$|p - p_1| < TOL$$
 then
OUTPUT (*p*); (*The procedure was successful*): STOP

5 Set
$$i = i + 1; q = f(p)$$

6 If
$$q \cdot q_1 < 0$$
 then set $p_0 = p_1; q_0 = q_1$

7 Set
$$p_1 = p; q_1 = q$$

8 OUTPUT ('Method failed after N_0 iterations, $N_0 =$ ', N_0); (*The procedure was unsuccessful*): STOP

Numerical Analysis (Chapter 2)

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Comparison with Newton & Secant Methods

Use the method of False Position to find a solution to $x = \cos x$, and compare the approximations with those given in a previous example which Newton's method and the Secant Method.

Numerical Analysis (Chapter 2)

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Comparison with Newton & Secant Methods

Use the method of False Position to find a solution to $x = \cos x$, and compare the approximations with those given in a previous example which Newton's method and the Secant Method.

To make a reasonable comparison we will use the same initial approximations as in the Secant method, that is, $p_0 = 0.5$ and $p_1 = \pi/4$.

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Comparison with Newton's Method & Secant Method

	False Position	Secant	Newton
п	<i>p</i> _n	p _n	pn
0	0.5	0.5	0.7853981635
1	0.7853981635	0.7853981635	0.7395361337
2	0.7363841388	0.7363841388	0.7390851781
3	0.7390581392	0.7390581392	0.7390851332
4	0.7390848638	0.7390851493	0.7390851332
5	0.7390851305	0.7390851332	
6	0.7390851332		

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Comparison with Newton's Method & Secant Method

	False Position	Secant	Newton
n	<i>p</i> _n	p _n	pn
0	0.5	0.5	0.7853981635
1	0.7853981635	0.7853981635	0.7395361337
2	0.7363841388	0.7363841388	0.7390851781
3	0.7390581392	0.7390581392	0.7390851332
4	0.7390848638	0.7390851493	0.7390851332
5	0.7390851305	0.7390851332	
6	0.7390851332		

Note that the False Position and Secant approximations agree through p_3 and that the method of False Position requires an additional iteration to obtain the same accuracy as the Secant method.

Numerical Analysis (Chapter 2)

Secant & Regula Falsi Methods

Final Remarks

Numerical Analysis (Chapter 2)

Secant & Regula Falsi Methods

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Final Remarks

• The added insurance of the method of False Position commonly requires more calculation than the Secant method, ...

Numerical Analysis (Chapter 2)

Secant & Regula Falsi Methods

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Final Remarks

- The added insurance of the method of False Position commonly requires more calculation than the Secant method, ...
- just as the simplification that the Secant method provides over Newton's method usually comes at the expense of additional iterations.

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Questions?

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Reference Material

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Exercise 14, Section 2.4

It can be shown (see, for example, Dahlquist and Å. Björck (1974), pp. 228–229), that if $\{p_n\}_{n=0}^{\infty}$ are convergent Secant method approximations to p, the solution to f(x) = 0, then a constant C exists with

$$|p_{n+1}-p| pprox C |p_n-p| |p_{n-1}-p|$$

for sufficiently large values of *n*. Assume $\{p_n\}$ converges to *p* of order α , and show that

$$lpha = (1 + \sqrt{5})/2$$

(*Note:* This implies that the order of convergence of the Secant method is approximately 1.62).

Return to the Secant Method

Dahlquist, G. and Å. Björck (Translated by N. Anderson), *Numerical methods*, Prentice-Hall, Englewood Cliffs, NJ, 1974.