## Solutions of Equations in One Variable

## Secant \＆Regula Falsi Methods

Numerical Analysis（9th Edition）<br>R L Burden \＆J D Faires<br>Beamer Presentation Slides<br>prepared by<br>John Carroll<br>Dublin City University

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## Outline

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(1) Secant Method: Derivation \& Algorithm
(2) Comparing the Secant \& Newton's Methods

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(3) The Method of False Position (Regula Falsi)

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## (2) Comparing the Secant \& Newton's Methods

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## Rationale for the Secant Method

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- Newton's method is an extremely powerful technique, but it has a major weakness: the need to know the value of the derivative of $f$ at each approximation.
- Frequently, $f^{\prime}(x)$ is far more difficult and needs more arithmetic operations to calculate than $f(x)$.


## Derivation of the Secant Method

$$
f^{\prime}\left(p_{n-1}\right)=\lim _{x \rightarrow p_{n-1}} \frac{f(x)-f\left(p_{n-1}\right)}{x-p_{n-1}} .
$$

## Circumvent the Derivative Evaluation

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If $p_{n-2}$ is close to $p_{n-1}$, then

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Using this approximation for $f^{\prime}\left(p_{n-1}\right)$ in Newton's formula gives

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p_{n}=p_{n-1}-\frac{f\left(p_{n-1}\right)\left(p_{n-1}-p_{n-2}\right)}{f\left(p_{n-1}\right)-f\left(p_{n-2}\right)}
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This technique is called the Secant method

## Secant Method: Using Successive Secants



## The Secant Method

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## Procedure

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## Procedure

- Starting with the two initial approximations $p_{0}$ and $p_{1}$, the approximation $p_{2}$ is the $x$-intercept of the line joining $\left(p_{0}, f\left(p_{0}\right)\right)$ and $\left(p_{1}, f\left(p_{1}\right)\right)$.


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- The approximation $p_{3}$ is the $x$-intercept of the line joining $\left(p_{1}, f\left(p_{1}\right)\right)$ and $\left(p_{2}, f\left(p_{2}\right)\right)$, and so on.


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- Note that only one function evaluation is needed per step for the Secant method after $p_{2}$ has been determined.


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- The approximation $p_{3}$ is the $x$-intercept of the line joining $\left(p_{1}, f\left(p_{1}\right)\right)$ and ( $\left.p_{2}, f\left(p_{2}\right)\right)$, and so on.
- Note that only one function evaluation is needed per step for the Secant method after $p_{2}$ has been determined.
- In contrast, each step of Newton's method requires an evaluation of both the function and its derivative.


## The Secant Method: Algorithm

To find a solution to $f(x)=0$ given initial approximations $p_{0}$ and $p_{1}$; tolerance $T O L$; maximum number of iterations $N_{0}$.

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3 \text { Set } p=p_{1}-q_{1}\left(p_{1}-p_{0}\right) /\left(q_{1}-q_{0}\right) . \quad\left(\text { Compute } p_{i}\right)
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4 If $\left|p-p_{1}\right|<T O L$ then
OUTPUT (p); (The procedure was successful.) STOP

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5 Set $i=i+1$
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$q_{0}=q_{1} ; p_{1}=p ; q_{1}=f(p)$
7 OUTPUT ('The method failed after $N_{0}$ iterations, $N_{0}=$ ', $N_{0}$ ); (The procedure was unsuccessful) STOP

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## (1) Secant Method: Derivation \& Algorithm

## (2) Comparing the Secant \& Newton's Methods

## (3) The Method of False Position (Regula Falsi)

## Comparing the Secant \& Newton's Methods

## Example: $f(x)=\cos x-x$

Use the Secant method to find a solution to $x=\cos x$, and compare the approximations with those given by Newton's method with $p_{0}=\pi / 4$.

## Formula for the Secant Method

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We need two initial approximations. Suppose we use $p_{0}=0.5$ and $p_{1}=\pi / 4$. Succeeding approximations are generated by the formula

$$
p_{n}=p_{n-1}-\frac{\left(p_{n-1}-p_{n-2}\right)\left(\cos p_{n-1}-p_{n-1}\right)}{\left(\cos p_{n-1}-p_{n-1}\right)-\left(\cos p_{n-2}-p_{n-2}\right)}, \quad \text { for } n \geq 2
$$

## Comparing the Secant \& Newton's Methods

Newton's Method for $f(x)=\cos (x)-x, p_{0}=\frac{\pi}{4}$

| $n$ | $p_{n-1}$ | $f\left(p_{n-1}\right)$ | $f^{\prime}\left(p_{n-1}\right)$ | $p_{n}$ | $\left\|p_{n}-p_{n-1}\right\|$ |
| :---: | ---: | ---: | ---: | ---: | ---: |
| 1 | 0.78539816 | -0.078291 | -1.707107 | 0.73953613 | 0.04586203 |
| 2 | 0.73953613 | -0.000755 | -1.673945 | 0.73908518 | 0.00045096 |
| 3 | 0.73908518 | -0.000000 | -1.673612 | 0.73908513 | 0.00000004 |
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- Because of the agreement of $p_{3}$ and $p_{4}$ we could reasonably expect this result to be accurate to the places listed.


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| ---: | ---: | ---: | ---: | ---: |
| 2 | 0.500000000 | 0.785398163 | 0.736384139 | 0.0490140246 |
| 3 | 0.785398163 | 0.736384139 | 0.739058139 | 0.0026740004 |
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- Comparing results, we see that the Secant Method approximation $p_{5}$ is accurate to the tenth decimal place, whereas Newton's method obtained this accuracy by $p_{3}$.


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- This is generally the case. Order of Conereane


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- The Secant method and Newton's method are often used to refine an answer obtained by another technique (such as the Bisection Method).
- Both methods require good first approximations but generally give rapid acceleration.


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## (1) Secant Method: Derivation \& Algorithm

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(3) The Method of False Position (Regula Falsi)

## The Method of False Position

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- The method of False Position (also called Regula Falsi) generates approximations in the same manner as the Secant method, but it includes a test to ensure that the root is always bracketed between successive iterations.
- Although it is not a method we generally recommend, it illustrates how bracketing can be incorporated.


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## Construction of the Method

- First choose initial approximations $p_{0}$ and $p_{1}$ with $f\left(p_{0}\right) \cdot f\left(p_{1}\right)<0$.


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- To decide which secant line to use to compute $p_{3}$, consider $f\left(p_{2}\right) \cdot f\left(p_{1}\right)$, or more correctly sgn $f\left(p_{2}\right) \cdot \operatorname{sgn} f\left(p_{1}\right)$ :


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- If $\operatorname{sgn} f\left(p_{2}\right) \cdot \operatorname{sgn} f\left(p_{1}\right)<0$, then $p_{1}$ and $p_{2}$ bracket a root. Choose $p_{3}$ as the $x$-intercept of the line joining $\left(p_{1}, f\left(p_{1}\right)\right)$ and $\left(p_{2}, f\left(p_{2}\right)\right)$.


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- If $\operatorname{sgn} f\left(p_{2}\right) \cdot \operatorname{sgn} f\left(p_{1}\right)<0$, then $p_{1}$ and $p_{2}$ bracket a root. Choose $p_{3}$ as the $x$-intercept of the line joining $\left(p_{1}, f\left(p_{1}\right)\right)$ and $\left(p_{2}, f\left(p_{2}\right)\right)$.
- If not, choose $p_{3}$ as the $x$-intercept of the line joining $\left(p_{0}, f\left(p_{0}\right)\right)$ and $\left(p_{2}, f\left(p_{2}\right)\right)$, and then interchange the indices on $p_{0}$ and $p_{1}$.


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- In a similar manner, once $p_{3}$ is found, the sign of $f\left(p_{3}\right) \cdot f\left(p_{2}\right)$ determines whether we use $p_{2}$ and $p_{3}$ or $p_{3}$ and $p_{1}$ to compute $p_{4}$.


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- In the latter case, a relabeling of $p_{2}$ and $p_{1}$ is performed.


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- In the latter case, a relabeling of $p_{2}$ and $p_{1}$ is performed.
- The relabelling ensures that the root is bracketed between successive iterations.


## Secant Method \& Method of False Position

Secant method


Method of False Position


In this illustration, the first three approximations are the same for both methods, but the fourth approximations differ.

## The Method of False Position: Algorithm

To find a solution to $f(x)=0$, given the continuous function $f$ on the interval [ $p_{0}, p_{1}$ ] (where $f\left(p_{0}\right)$ and $f\left(p_{1}\right)$ have opposite signs) tolerance TOL and maximum number of iterations $N_{0}$.

## The Method of False Position: Algorithm

To find a solution to $f(x)=0$, given the continuous function $f$ on the interval $\left[p_{0}, p_{1}\right]$ (where $f\left(p_{0}\right)$ and $f\left(p_{1}\right)$ have opposite signs) tolerance $T O L$ and maximum number of iterations $N_{0}$.

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$$
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OUTPUT (p); (The procedure was successful): STOP

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5 Set $i=i+1 ; q=f(p)$

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4 If $\left|p-p_{1}\right|<T O L$ then
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5 Set $i=i+1 ; q=f(p)$
6 If $q \cdot q_{1}<0$ then set $p_{0}=p_{1} ; q_{0}=q_{1}$
7 Set $p_{1}=p ; q_{1}=q$

## The Method of False Position: Algorithm

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3 Set \(p=p_{1}-q_{1}\left(p_{1}-p_{0}\right) /\left(q_{1}-q_{0}\right)\). (Compute \(\left.p_{i}\right)\)
```

4 If $\left|p-p_{1}\right|<T O L$ then
OUTPUT (p); (The procedure was successful): STOP
5 Set $i=i+1 ; q=f(p)$
6 If $q \cdot q_{1}<0$ then set $p_{0}=p_{1} ; q_{0}=q_{1}$
7 Set $p_{1}=p ; q_{1}=q$
8 OUTPUT ('Method failed after $N_{0}$ iterations, $N_{0}=$ ', $N_{0}$ ); (The procedure was unsuccessful): STOP

## The Method of False Position: Numerical Calculations

## Comparison with Newton \& Secant Methods

Use the method of False Position to find a solution to $x=\cos x$, and compare the approximations with those given in a previous example which Newton's method and the Secant Method.

## The Method of False Position: Numerical Calculations

## Comparison with Newton \& Secant Methods

Use the method of False Position to find a solution to $x=\cos x$, and compare the approximations with those given in a previous example which Newton's method and the Secant Method.

To make a reasonable comparison we will use the same initial approximations as in the Secant method, that is, $p_{0}=0.5$ and $p_{1}=\pi / 4$.

## The Method of False Position: Numerical Calculations

Comparison with Newton's Method \& Secant Method

|  | False Position | Secant | Newton |
| :--- | :--- | :--- | :--- |
| $n$ | $p_{n}$ | $p_{n}$ | $p_{n}$ |
| 0 | 0.5 | 0.5 | 0.7853981635 |
| 1 | 0.7853981635 | 0.7853981635 | 0.7395361337 |
| 2 | 0.7363841388 | 0.7363841388 | 0.7390851781 |
| 3 | 0.7390581392 | 0.7390581392 | 0.7390851332 |
| 4 | 0.7390848638 | 0.7390851493 | 0.7390851332 |
| 5 | 0.7390851305 | 0.7390851332 |  |
| 6 | 0.7390851332 |  |  |

## The Method of False Position: Numerical Calculations

Comparison with Newton's Method \& Secant Method

|  | False Position | Secant | Newton |
| :--- | :--- | :--- | :--- |
| $n$ | $p_{n}$ | $p_{n}$ | $p_{n}$ |
| 0 | 0.5 | 0.5 | 0.7853981635 |
| 1 | 0.7853981635 | 0.7853981635 | 0.7395361337 |
| 2 | 0.7363841388 | 0.7363841388 | 0.7390851781 |
| 3 | 0.7390581392 | 0.7390581392 | 0.7390851332 |
| 4 | 0.7390848638 | 0.7390851493 | 0.7390851332 |
| 5 | 0.7390851305 | 0.7390851332 |  |
| 6 | 0.7390851332 |  |  |

Note that the False Position and Secant approximations agree through $p_{3}$ and that the method of False Position requires an additional iteration to obtain the same accuracy as the Secant method.

## The Method of False Position

## Final Remarks

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- The added insurance of the method of False Position commonly requires more calculation than the Secant method, ...
- just as the simplification that the Secant method provides over Newton's method usually comes at the expense of additional iterations.


## Questions?

## Reference Material

## Order of Convergence of the Secant Method

## Exercise 14, Section 2.4

It can be shown (see, for example, Dahlquist and Å. Björck (1974), pp. 228-229), that if $\left\{p_{n}\right\}_{n=0}^{\infty}$ are convergent Secant method approximations to $p$, the solution to $f(x)=0$, then a constant $C$ exists with

$$
\left|p_{n+1}-p\right| \approx C\left|p_{n}-p\right|\left|p_{n-1}-p\right|
$$

for sufficiently large values of $n$. Assume $\left\{p_{n}\right\}$ converges to $p$ of order $\alpha$, and show that

$$
\alpha=(1+\sqrt{5}) / 2
$$

(Note: This implies that the order of convergence of the Secant method is approximately 1.62).

Dahlquist, G. and Å. Björck (Translated by N. Anderson), Numerical methods, Prentice-Hall, Englewood Cliffs, NJ, 1974.

