Interpolation & Polynomial Approximation

Lagrange Interpolating Polynomials I

Numerical Analysis (9th Edition) R L Burden & J D Faires

Beamer Presentation Slides prepared by John Carroll Dublin City University

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Inaccuracy of Taylor Polynomials

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Inaccuracy of Taylor Polynomials



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Inaccuracy of Taylor Polynomials

- 3 Constructing the Lagrange Polynomial
- Example: Second-Degree Lagrange Interpolating Polynomial



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Weierstrass Approximation Theorem

Algebraic Polynomials

Numerical Analysis (Chapter 3)

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Weierstrass Approximation Theorem

Algebraic Polynomials

One of the most useful and well-known classes of functions mapping the set of real numbers into itself is the algebraic polynomials, the set of functions of the form

$$P_n(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$$

where *n* is a nonnegative integer and a_0, \ldots, a_n are real constants.

Weierstrass Approximation Theorem

$$P_n(x) = a_n x^n + a_{n-1} x^{n-1} + \cdots + a_1 x + a_0,$$

Algebraic Polynomials (Cont'd)

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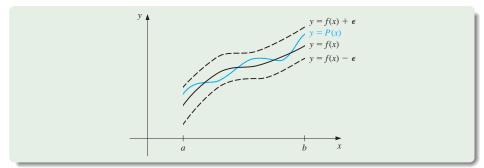
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- By this we mean that given any function, defined and continuous on a closed and bounded interval, there exists a polynomial that is as "close" to the given function as desired.

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- One reason for their importance is that they uniformly approximate continuous functions.
- By this we mean that given any function, defined and continuous on a closed and bounded interval, there exists a polynomial that is as "close" to the given function as desired.
- This result is expressed precisely in the Weierstrass Approximation Theorem.



Weierstrass Approximation Theorem

Suppose that *f* is defined and continuous on [*a*, *b*]. For each $\epsilon > 0$, there exists a polynomial *P*(*x*), with the property that

$$|f(x) - P(x)| < \epsilon$$
, for all x in [a, b].

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Benefits of Algebraic Polynomials

Numerical Analysis (Chapter 3)

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 Another important reason for considering the class of polynomials in the approximation of functions is that the derivative and indefinite integral of a polynomial are easy to determine and are also polynomials.

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Benefits of Algebraic Polynomials

- Another important reason for considering the class of polynomials in the approximation of functions is that the derivative and indefinite integral of a polynomial are easy to determine and are also polynomials.
- For these reasons, polynomials are often used for approximating continuous functions.

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Inaccuracy of Taylor Polynomials

- 3 Constructing the Lagrange Polynomial
- Example: Second-Degree Lagrange Interpolating Polynomial

The Lagrange Polynomial: Taylor Polynomials

Interpolating with Taylor Polynomials

Numerical Analysis (Chapter 3)

Interpolating with Taylor Polynomials

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- Given this prominence, you might expect that polynomial interpolation would make heavy use of these functions.
- However this is not the case.
- The Taylor polynomials agree as closely as possible with a given function at a specific point, but they concentrate their accuracy near that point.
- A good interpolation polynomial needs to provide a relatively accurate approximation over an entire interval, and Taylor polynomials do not generally do this.

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Example: $f(x) = e^x$

We will calculate the first six Taylor polynomials about $x_0 = 0$ for $f(x) = e^x$.

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Note

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The Taylor polynomials are as follows:

Taylor Polynomials for $f(x) = e^x$ about $x_0 = 0$

$$P_0(x) = 1$$

$$P_{1}(x) = 1 + x$$

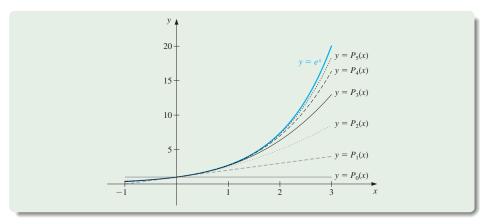
$$P_{2}(x) = 1 + x + \frac{x^{2}}{2}$$

$$P_{3}(x) = 1 + x + \frac{x^{2}}{2} + \frac{x^{3}}{6}$$

$$P_4(x) = 1 + x + \frac{x^2}{2} + \frac{x^3}{6} + \frac{x^4}{24}$$

$$P_5(x) = 1 + x + \frac{x^2}{2} + \frac{x^3}{6} + \frac{x^4}{24} + \frac{x^5}{120}$$

Taylor Polynomials for $f(x) = e^x$ about $x_0 = 0$



Notice that even for the higher-degree polynomials, the error becomes progressively worse as we move away from zero.

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Taylor Polynomials for $f(x) = \frac{1}{x}$ about $x_0 = 1$

Example: A more extreme case

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Taylor Polynomials for $f(x) = \frac{1}{x}$ about $x_0 = 1$

Example: A more extreme case

- Although better approximations are obtained for $f(x) = e^x$ if higher-degree Taylor polynomials are used, this is not true for all functions.
- Consider, as an extreme example, using Taylor polynomials of various degrees for f(x) = ¹/_x expanded about x₀ = 1 to approximate f(3) = ¹/₃.

Taylor Polynomials for $f(x) = \frac{1}{x}$ about $x_0 = 1$

Calculations

Numerical Analysis (Chapter 3)

Taylor Polynomials for $f(x) = \frac{1}{x}$ about $x_0 = 1$

Calculations

Since

$$f(x) = x^{-1}, f'(x) = -x^{-2}, f''(x) = (-1)^2 2 \cdot x^{-3},$$

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and, in general,

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and, in general,

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the Taylor polynomials are

$$P_n(x) = \sum_{k=0}^n \frac{f^{(k)}(1)}{k!} (x-1)^k = \sum_{k=0}^n (-1)^k (x-1)^k.$$

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Taylor Polynomials for $f(x) = \frac{1}{x}$ about $x_0 = 1$

To Approximate $\overline{f(3)} = \frac{1}{3}$ by $P_n(3)$

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Taylor Polynomials for $f(x) = \frac{1}{x}$ about $x_0 = 1$

To Approximate $f(3) = \frac{1}{3}$ by $P_n(3)$

• To approximate $f(3) = \frac{1}{3}$ by $P_n(3)$ for increasing values of *n*, we obtain the values shown below — rather a dramatic failure!

Taylor Polynomials for $f(x) = \frac{1}{x}$ about $x_0 = 1$

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n	0	1	2	3	4	5	6	7	
$\overline{P_n(3)}$	1	-1	3	-5	11	-21	43	-85	

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Example

The Lagrange Polynomial: Taylor Polynomials

Footnotes

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 For the Taylor polynomials, all the information used in the approximation is concentrated at the single number x₀, so these polynomials will generally give inaccurate approximations as we move away from x₀.

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Footnotes

- For the Taylor polynomials, all the information used in the approximation is concentrated at the single number x₀, so these polynomials will generally give inaccurate approximations as we move away from x₀.
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- This limits Taylor polynomial approximation to the situation in which approximations are needed only at numbers close to x₀.
- For ordinary computational purposes, it is more efficient to use methods that include information at various points.
- The primary use of Taylor polynomials in numerical analysis is not for approximation purposes, but for the derivation of numerical techniques and error estimation.

Outline



Inaccuracy of Taylor Polynomials

3 Constructing the Lagrange Polynomial

Example: Second-Degree Lagrange Interpolating Polynomial

Polynomial Interpolation

Numerical Analysis (Chapter 3)

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Polynomial Interpolation

• The problem of determining a polynomial of degree one that passes through the distinct points

 (x_0, y_0) and (x_1, y_1)

is the same as approximating a function *f* for which

$$f(x_0) = y_0$$
 and $f(x_1) = y_1$

by means of a first-degree polynomial interpolating, or agreeing with, the values of f at the given points.

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• Using this polynomial for approximation within the interval given by the endpoints is called polynomial interpolation.

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Define the functions

$$L_0(x) = rac{x - x_1}{x_0 - x_1}$$
 and $L_1(x) = rac{x - x_0}{x_1 - x_0}$.

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$$L_0(x) = rac{x-x_1}{x_0-x_1}$$
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Definition

The linear Lagrange interpolating polynomial though (x_0, y_0) and (x_1, y_1) is

$$P(x) = L_0(x)f(x_0) + L_1(x)f(x_1) = \frac{x - x_1}{x_0 - x_1}f(x_0) + \frac{x - x_0}{x_1 - x_0}f(x_1).$$

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$$P(x) = L_0(x)f(x_0) + L_1(x)f(x_1) = \frac{x - x_1}{x_0 - x_1}f(x_0) + \frac{x - x_0}{x_1 - x_0}f(x_1).$$

Note that

$$L_0(x_0) = 1$$
, $L_0(x_1) = 0$, $L_1(x_0) = 0$, and $L_1(x_1) = 1$,

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which implies that

$$P(x_0) = 1 \cdot f(x_0) + 0 \cdot f(x_1) = f(x_0) = y_0$$

and

$$P(x_1) = 0 \cdot f(x_0) + 1 \cdot f(x_1) = f(x_1) = y_1.$$

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and

$$P(x_1) = 0 \cdot f(x_0) + 1 \cdot f(x_1) = f(x_1) = y_1.$$

So *P* is the unique polynomial of degree at most 1 that passes through (x_0, y_0) and (x_1, y_1) .

Numerical Analysis (Chapter 3)

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Example: Linear Interpolation

Determine the linear Lagrange interpolating polynomial that passes through the points (2, 4) and (5, 1).

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Solution

In this case we have

$$L_0(x) = \frac{x-5}{2-5} = -\frac{1}{3}(x-5)$$
 and $L_1(x) = \frac{x-2}{5-2} = \frac{1}{3}(x-2),$

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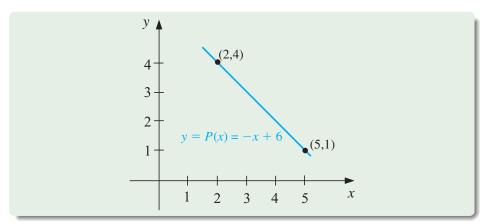
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 and $L_1(x) = \frac{x-2}{5-2} = \frac{1}{3}(x-2)$,

SO

$$P(x) = -\frac{1}{3}(x-5) \cdot 4 + \frac{1}{3}(x-2) \cdot 1 = -\frac{4}{3}x + \frac{20}{3} + \frac{1}{3}x - \frac{2}{3} = -x + 6.$$

Example

The Lagrange Polynomial: The Linear Case



The linear Lagrange interpolating polynomial that passes through the points (2, 4) and (5, 1).

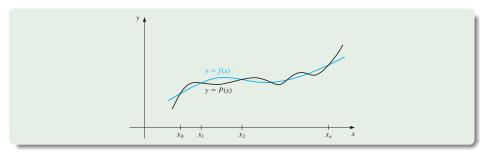
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The Lagrange Polynomial: Degree *n* Construction



To generalize the concept of linear interpolation, consider the construction of a polynomial of degree at most *n* that passes through the n + 1 points

$$(x_0, f(x_0)), (x_1, f(x_1)), \ldots, (x_n, f(x_n)).$$

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Constructing the Degree *n* Polynomial

Constructing the Degree n Polynomial

• We first construct, for each k = 0, 1, ..., n, a function $L_{n,k}(x)$ with the property that $L_{n,k}(x_i) = 0$ when $i \neq k$ and $L_{n,k}(x_k) = 1$.

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- To satisfy $L_{n,k}(x_i) = 0$ for each $i \neq k$ requires that the numerator of $L_{n,k}(x)$ contain the term

$$(x - x_0)(x - x_1) \cdots (x - x_{k-1})(x - x_{k+1}) \cdots (x - x_n).$$

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To satisfy L_{n,k}(x_k) = 1, the denominator of L_{n,k}(x) must be this same term but evaluated at x = x_k.

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Thus

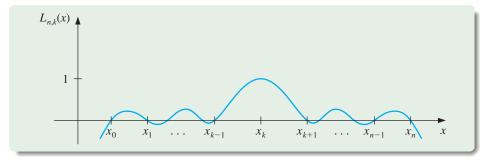
$$L_{n,k}(x) = \frac{(x-x_0)\cdots(x-x_{k-1})(x-x_{k+1})\cdots(x-x_n)}{(x_k-x_0)\cdots(x_k-x_{k-1})(x_k-x_{k+1})\cdots(x_k-x_n)}.$$

Numerical Analysis (Chapter 3)

Example

The Lagrange Polynomial: The General Case

$$L_{n,k}(x) = \frac{(x-x_0)\cdots(x-x_{k-1})(x-x_{k+1})\cdots(x-x_n)}{(x_k-x_0)\cdots(x_k-x_{k-1})(x_k-x_{k+1})\cdots(x_k-x_n)}.$$



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Theorem: *n*-th Lagrange interpolating polynomial

Numerical Analysis (Chapter 3)

Theorem: *n*-th Lagrange interpolating polynomial

If x_0, x_1, \ldots, x_n are n + 1 distinct numbers and f is a function whose values are given at these numbers,

Theorem: *n*-th Lagrange interpolating polynomial

If $x_0, x_1, ..., x_n$ are n + 1 distinct numbers and f is a function whose values are given at these numbers, then a unique polynomial P(x) of degree at most n exists with

$$f(x_k) = P(x_k)$$
, for each $k = 0, 1, ..., n$.

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, for each $k = 0, 1, ..., n$.

This polynomial is given by

$$P(x) = f(x_0)L_{n,0}(x) + \dots + f(x_n)L_{n,n}(x) = \sum_{k=0}^n f(x_k)L_{n,k}(x)$$

where, for each k = 0, 1, ..., n, $L_{n,k}(x)$ is defined as follows:

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Definition of $L_{n,k}(x)$

$$L_{n,k}(x) = \frac{(x-x_0)(x-x_1)\cdots(x-x_{k-1})(x-x_{k+1})\cdots(x-x_n)}{(x_k-x_0)(x_k-x_1)\cdots(x_k-x_{k-1})(x_k-x_{k+1})\cdots(x_k-x_n)}$$

=
$$\prod_{\substack{i=0\\i\neq k}}^n \frac{(x-x_i)}{(x_k-x_i)}$$

We will write $L_{n,k}(x)$ simply as $L_k(x)$ when there is no confusion as to its degree.

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Outline



2 Inaccuracy of Taylor Polynomials

- 3 Constructing the Lagrange Polynomial
- Example: Second-Degree Lagrange Interpolating Polynomial

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Example: $f(x) = \frac{1}{x}$

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Example: $f(x) = \frac{1}{x}$

(a) Use the numbers (called nodes) $x_0 = 2$, $x_1 = 2.75$ and $x_2 = 4$ to find the second Lagrange interpolating polynomial for $f(x) = \frac{1}{x}$.

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Example: $f(x) = \frac{1}{x}$

(a) Use the numbers (called nodes) $x_0 = 2$, $x_1 = 2.75$ and $x_2 = 4$ to find the second Lagrange interpolating polynomial for $f(x) = \frac{1}{x}$.

(b) Use this polynomial to approximate $f(3) = \frac{1}{3}$.

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Part (a): Solution

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Part (a): Solution

We first determine the coefficient polynomials $L_0(x)$, $L_1(x)$, and $L_2(x)$:

$$L_0(x) = \frac{(x-2.75)(x-4)}{(2-2.5)(2-4)} = \frac{2}{3}(x-2.75)(x-4)$$
$$L_1(x) = \frac{(x-2)(x-4)}{(2.75-2)(2.75-4)} = -\frac{16}{15}(x-2)(x-4)$$
$$L_2(x) = \frac{(x-2)(x-2.75)}{(4-2)(4-2.5)} = \frac{2}{5}(x-2)(x-2.75)$$

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Part (a): Solution

We first determine the coefficient polynomials $L_0(x)$, $L_1(x)$, and $L_2(x)$:

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$$L_2(x) = \frac{(x-2)(x-2.75)}{(4-2)(4-2.5)} = \frac{2}{5}(x-2)(x-2.75)$$

Also, since $f(x) = \frac{1}{x}$:

 $f(x_0) = f(2) = 1/2,$ $f(x_1) = f(2.75) = 4/11,$ $f(x_2) = f(4) = 1/4$

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Part (a): Solution (Cont'd)

Therefore, we obtain

$$P(x) = \sum_{k=0}^{2} f(x_k) L_k(x)$$

= $\frac{1}{3} (x - 2.75)(x - 4) - \frac{64}{165} (x - 2)(x - 4) + \frac{1}{10} (x - 2)(x - 2.75)$
= $\frac{1}{22} x^2 - \frac{35}{88} x + \frac{49}{44}.$

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Example

The Lagrange Polynomial: 2nd Degree Polynomial

$$P(x) = \frac{1}{22}x^2 - \frac{35}{88}x + \frac{49}{44}$$

(b) Use this polynomial to approximate $f(3) = \frac{1}{3}$.

Part (b): Solution

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$$P(x) = \frac{1}{22}x^2 - \frac{35}{88}x + \frac{49}{44}$$

(b) Use this polynomial to approximate $f(3) = \frac{1}{3}$.

Part (b): Solution

An approximation to $f(3) = \frac{1}{3}$ is

$$f(3) \approx P(3) = \frac{9}{22} - \frac{105}{88} + \frac{49}{44} = \frac{29}{88} \approx 0.32955$$

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$$P(x) = \frac{1}{22}x^2 - \frac{35}{88}x + \frac{49}{44}$$

(b) Use this polynomial to approximate $f(3) = \frac{1}{3}$.

Part (b): Solution

An approximation to $f(3) = \frac{1}{3}$ is

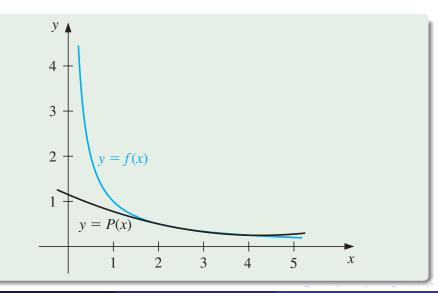
$$f(3) \approx P(3) = \frac{9}{22} - \frac{105}{88} + \frac{49}{44} = \frac{29}{88} \approx 0.32955.$$

Earlier, we we found that no Taylor polynomial expanded about $x_0 = 1$ could be used to reasonably approximate f(x) = 1/x at x = 3.

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Second Lagrange interpolating polynomial for $f(x) = \frac{1}{x}$



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Lagrange Interpolating Polynomials I